

Mirta Mataija¹

Mirjana Rakamarić Šegić²

Franciska Jozić³

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SOLVING THE TRAVELLING SALESMAN PROBLEM USING THE BRANCH AND BOUND METHOD⁴

ABSTRACT

The goal of this paper is to optimize delivering of packages at five randomly chosen addresses in the city of Rijeka. This problem is also known as the Travelling Salesman Problem and it is an NP hard problem. To achieve this goal, the concepts of a Hamilton path and cycle, as well as a Hamilton graph are defined. The theoretical basis for the branch and bound method is also given. The use of this method in the process of finding a solution for a problem is provided at the end of this paper.

Key words: Travelling Salesman Problem, Branch and Bound Method, Hamilton path, Hamilton cycle, NP complete problem, NP hard problem

1. INTRODUCTION

The Travelling Salesman Problem is one of the most studied problems in mathematical optimization. The possibility to apply this problem to various human activities is what it makes one of the most recognizable mathematical problems without an ideal solution so far.

The formulation of the problem is simple. The travelling salesman needs to pass through several towns and return to the starting point of his travel, making the shortest trip possible. Instead of examining the shortest route, one could examine the one that costs the least, one that allows the greatest flow of information, etc.

By its nature, the TSP falls into the category of NP-complete problems; meaning there is no algorithm that would provide a solution for the problem in terms of polynomial time but if the solution appears, one could test it and conclude whether it is an optimal one.

The goal of this research is to optimize the delivery of packages to appointed addresses in Rijeka. The delivery man has to deliver packages using the most efficient and shortest route moving from the distribution center to which he is required to return to after the delivery of the last package. This is in fact a Travelling Salesman Problem (Bosančić, V. Golemac, A. Vojković T.) and it can be solved using the branch and bound method (Pielić, M).

¹ MSc, Lecturer, Polytechnic of Rijeka, Vukovarska 58, 51000 Rijeka, Croatia. E-mail: mirta.mataija@veleri.hr

² MSc, Senior Lecturer, Polytechnic of Rijeka, Vukovarska 58, 51000 Rijeka, Croatia. E-mail: mrakams@veleri.hr

³ Spec. ing. traff., Teacher, Secondary Traffic School in Rijeka, Jože Vlahovića 10, Rijeka, Croatia. E-mail: franciskajozic@yahoo.com

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The paper consists of four parts. The Travelling Salesman Problem as well as the basic definitions of graph theories are provided in the second part. The theoretical basis for the branch and bound method is elaborated in the third part. Along with the theoretical basis, the algorithmic display of the method is provided. In the fourth and final part the method is used on the subject of the research.

2. THE TRAVELLING SALESMAN PROBLEM

In order to use mathematical methods in solving the Travelling Salesman Problem one needs to translate it to the language of a graph theory. The first step is to define several terms (Veljan, D.; Pašagić, H.).

Definition 1.1. Graph GG is an ordered pair $G = (V, R)G = (V, R)$ where $V \neq \emptyset V \neq \emptyset$ is a set of vertices of the graph while $R \subseteq V \times V R \subseteq V \times V$ is a set of edges or arcs of the GG graph.

In line with the definition, the vertices of graphs will be marked with $v_i v_i$, and the edges with $e_{ij} e_{ij}$. Mark $e_{ij} e_{ij}$ tells us that the given edge is incident (connected) with the vertices $v_i v_i$ and $v_j v_j$.

Definition 1.2. The path in the graph is $W := v_{i_0} e_{i_0 i_1} v_{i_1} \dots e_{i_{k-1} i_k} v_{i_k}$
 $W := v_{i_0} e_{i_0 i_1} v_{i_1} \dots e_{i_{k-1} i_k} v_{i_k}$ of the string in which all the vertices are different. The cycle is the path in which $v_{i_0} = v_{i_k} v_{i_0} = v_{i_k}$

Definition 1.3. a Hamilton path (cycle) in graph GG is the path (cycle) that contains all the vertices of graph GG . The graph is called a Hamilton graph if it contains a Hamilton cycle.

Definition 1.4. Weighted graph or a network is a graph in which all the edges have their appointed real numbers. The number $d_{ij} d_{ij}$ is appointed to the edge $e_{ij} e_{ij}$ and it is called the weight of the edge or simply - weight.

According to the above mentioned definitions one could conclude that the solution for the Travelling Salesman Problem is equivalent to finding the Hamilton cycle with the least weight in the network.

The Travelling Salesman Problem in its core is a problem of binary linear programming. The following codes are introduced (Perić, T.):

- $x_{ij} x_{ij}$ marks the binary variables as follows:

$$x_{ij} = \begin{cases} 1 & \text{if the salesman is travelling from town } i \text{ to town } j \\ 0 & \text{if the salesman is not travelling from town } i \text{ to town } j \end{cases}$$
- The distance between the towns i and j is marked with $d_{ij} d_{ij}$.

The Travelling Salesman Problem can be written as follows (Perić, T.):

$$F = \text{Min} \sum_{i=1}^n \sum_{j=1}^n d_{ij} x_{ij}$$

$$\sum_{j=1}^n x_{ij} = 1; i = 1, \dots, n$$

$$\sum_{i=1}^n x_{ij} = 1; j = 1, \dots, n$$

$$x_{ij} = 0 \text{ or } 1; x_{ij} = 0 \text{ or } 1.$$

The objective function is marked with F . The limitation should also be included into the program

$$x_{i_1 i_2} + x_{i_2 i_3} + \dots + x_{i_r i_1} \leq r - 1$$

in order to prevent the salesman returning to one of the towns he has already been to before he has visited all the towns. In other words, with these limitations the possibility of the appearance of under-cycles in the network is prevented. Since variables x_{ij} can only take a 0 or 1 state, this problem has a finite number of solutions.

3. THE BRANCH AND BOUND METHOD

While solving the Travelling Salesman Problem two approaches can be used. The first one is to find the correct solution, the optimal Hamilton cycle in the graph. Generally speaking, this is not so hard to achieve – first one has to find all the Hamilton cycles and choose the one with the minimal weight (Ivić, M.). However, the problem arises even in the case of a low number of vertices. Namely, the number of Hamilton cycles in the graph is $(n-1)!(n-1)!$ where n signifies the number of vertices of the graph. Number of cycles possible for $n = 10$ is 362880 while the number of cycles for $n = 20$ equals 121645100408832000.

The complexity of this particular problem is $O(n!)O(n!)$ and it is virtually useless when the number of vertices (entry data) exceeds 10 (Carić, T.).

The second approach consists of pursuing the “good enough” approximate solution.

The branch and bound method provides a correct solution for the given problem. It is suitable for use when the number of vertices of graphs does not exceed 60, which is sufficient when it comes to problems such as package delivery.

This method is based on the idea that the sets are divided into two disjoint subsets at every step of the process - branching. Furthermore, one subset contains the path between the two selected towns and the other subset does not. For each of these subsets the lower restriction (bound) is calculated for the duration or for travel expenses. Finally, the subset which exceeds the estimated lower bound is eliminated.

The procedure of branching is represented by a tree where the top is marked by the branching points of the set of solutions, and the edges mark the path between the two contiguous vertices in the graph which are used to model the problem and inside which the shortest Hamilton cycle is pursued.

The knots in the branching tree are labelled with the "etiquettes" which represent the lowest binding point for the objective function.

"Weightings" are assigned to the edges and they mark with " (p, q) " " (p, q) " the routes that are travelled or with " $non(p, q)$ " " $non(p, q)$ " those bypassed.

A way to represent and use this method with data tables is demonstrated since they are clearly suitable for any future computer applications (Perić, T.).

The steps of the algorithm for the Travelling Salesman Problem using the bound and branch method are as follows:

Step 1: Drawing a table

A table of distance between the given vertices is drawn. The distance between the vertices i and j are marked with d_{ij} . If the two vertices are not contiguous they are marked with $d_{ij} = \infty$. The $d_{ii} = \infty$ mark to signify and prevent the algorithm to choose the path $i \rightarrow ii \rightarrow i$ is also appointed.

Step 2: The reduction of the table

In every row of the table, the smallest element is located and marked with r_i :

$$r_i = \min_j d_{ij}, \quad j = 1, \dots, n, \quad r_i = \min_j d_{ij}, \quad j = 1, \dots, n$$

The smallest elements in columns are calculated using the following formula:

$$c_j = \min_i (d_{ij} - r_i) \quad c_j = \min_i (d_{ij} - r_i).$$

The reduction of the table is calculated with the formula:

$$d'_{ij} = d_{ij} - r_i - c_j$$

Step 3: The calculation of the lower boundary

The lower boundary of the duration of the travel is calculated

$$b = \sum_{i=1}^n r_i + \sum_{j=1}^n c_j$$

and assigned, which bounds to the knots of the branching tree as etiquette.

Step 3': The calculation of the lower boundary

b is equalized with the etiquette of the knot in which the branching is performed.

Step 4: Branching

The top from which the branching will start is chosen. All the addresses in the reduced table are found, the $(i, j)(i, j)$ paths, for which we can state that $d'_{ij} = 0d'_{ij} = 0$. For each of these, the "penalty" for not utilizing the trajectory $(i, j)(i, j)$ is calculated. The penalty is calculated with the formula:

$$\pi_{ij} = \min_j d'_{ij} + \min_i d'_{ij}$$

The branching is initiated with the trajectory which is assigned the maximum "penalty".

$$\pi = \max_{ij} \pi_{ij}$$

$(p, q)(p, q)$ are used to mark the route with the maximum penalty.

Step 5: Etiquette calculating

The etiquette of the knot contiguous to the edge which has a "weighting" $(p, q)(p, q)$ is calculated. In the reduction table $d_{qp} = \infty d_{qp} = \infty$ is assigned to signify the restriction towards the traveller, preventing him from returning from town q to town p . Furthermore, all the possibilities of closing the cycle prior to passing all the vertices of the graph need to be blocked. The next step is to remove the p line and q column from that table and repeat steps 2 and 3. The sum of the reduced elements is marked with $\sigma\sigma$.

Step 6: Drawing the branching tree

In the branching tree, we assign the b etiquette to the knot from which the branching started. The edges that exit this knot are assigned with "weightings" $(p, q)(p, q)$ and $non(p, q)non(p, q)$. The contiguous knot to the $non(p, q)non(p, q)$ edge is assigned with the $b + \pi b + \pi$ etiquette. The contiguous knot to the $(p, q)(p, q)$ edge is on the other hand assigned with the $b + \sigma b + \sigma$ etiquette.

Step 7: Locating the knot with the smallest etiquette

One should try to pinpoint the knot with the smallest etiquette in the branching tree and repeat the procedure – steps 1-6 are the same with the exception of step 3 which is replaced with step 3'.

The algorithm is completed when the table contains only routes which, if not used, lead to the solution that is the trajectory of infinite duration.

4. PROBLEM SOLUTION

The aim of this research paper is to optimize the delivery of packages to the appointed addresses in Rijeka. This is in fact a Travelling Salesman Problem and it can be solved using the branch and bound method (Pielić, M). This method is useful when the number of addresses does not exceed 60. In this case the appointed number of addresses is 5 and the method can be applied without the use of computers, as it is shown in the research.

The branch and bound method is used to optimize the package delivery to five addresses in the town of Rijeka. These are the following addresses:

1. Kršinićeva
2. Giuseppe Carabine
3. Antuna Kosića Rike
4. Simonettieva
5. Crnčićeva.

The distance between them in meters is provided in Table 1. (Jozić, F.)

The algorithm described in the previous section is used to calculate the optimal route to deliver the packages to these addresses.

Step 1

Table 1. Distance between the streets

addresses	1	2	3	4	5
1	∞	600	1000	1900	1100
2	600	∞	1900	1900	1500
3	1000	1900	∞	1700	1200
4	1900	1900	1700	∞	1900
5	1100	1500	1200	1900	∞

Source: authors

Step 2

Table 2 - Locating the minimal elements in lines

addresses	1	2	3	4	5	r_i
1	∞	600	1000	1900	1100	600
2	600	∞	1900	1900	1500	600
3	1000	1900	∞	1700	1200	1000
4	1900	1900	1700	∞	1900	1700
5	1100	1500	1200	1900	∞	1100

Source: authors

The minimal element in the i -row, $i = 1, \dots, 5$, calculated using the formula:

$$r_i = \min_j d_{ij}, \quad j = 1, \dots, n; \quad nr_i = \min_j d_{ij}, \quad j = 1, \dots, n.$$

Table 3 – Locating the minimal elements in columns

addresses	1	2	3	4	5	r_i
1	∞	600	1000	1900	1100	600
2	600	∞	1900	1900	1500	600
3	1000	1900	∞	1700	1200	1000
4	1900	1900	1700	∞	1900	1700
5	1100	1500	1200	1900	∞	1100
c_j	0	0	0	700	200	

Source: authors

The minimal element in the j -row, $j = 1, \dots, 5$, calculated using the formula:

$$c_j = \min_i(d_{ij}c_j = \min_i(d_{ij}-r_i).$$

Table 4 – Reduced table

addresses	1	2	3	4	5	r_i
1	∞	0	400	600	300	600
2	0	∞	1300	600	700	600
3	0	900	∞	0	0	1000
4	200	200	0	∞	0	1700
5	0	400	100	100	∞	1100
c_j	0	0	0	700	200	

Source: authors

The reduction of the table is done using the formula:

$$d'_{ij} = d_{ij} - r_i - c_j d'_{ij} = d_{ij} - r_i - c_j.$$

Step 3

In step 3, the lower boundary of the duration of the travel route is calculated using the formula

$$b = \sum_{i=1}^n r_i + \sum_{j=1}^n c_j b = \sum_{i=1}^n r_i + \sum_{j=1}^n c_j$$

$$b = 5900$$

Step 4

The top from which the branching will commence is found. "Penalty" for not using the route $i-j$ is calculated using the formula:

$$\pi_{ij} = \min_j d'_{ij} + \min_i d'_{ij} \pi_{ij} = \min_j d'_{ij} + \min_i d'_{ij}$$

The branching commences with the route that carries the maximum "penalty" provided by the formula $\pi = \max_{i,j} \pi_{ij}$

In this case, the maximum "penalty" is appointed for not using the 2-1 route and it is 600 meters:

$$\pi = \pi_{21} = 600$$

Step 5

The second row and first column are removed from the starting table given the fact that the route 2-1 has the maximum penalty. This table is then repeatedly used through steps 2 and 3 producing Table 5. In this table, the elements from column r_i and row c_j are aggregated. Their sum is marked with σ . When σ is aggregated with the lower boundary b calculated in step 2, the lower boundary of the route $i-j$, in this case 2-1, is calculated.

Table 5 – Table without the second line and first column

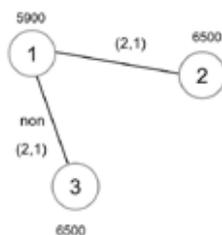
addresses	2	3	4	5	r_i
1	∞	400	600	300	300
3	900	∞	0	0	0
4	200	0	∞	0	0
5	400	100	100	∞	100
c_j	200	0	0	0	

Source: authors

$$\sigma = 600$$

Step 6

In the branching tree, the top is marked with 1 and the edges that stem from it have "ponders" (2,1) or rather non(2,1) depending on the usage of the route 2-1 for package delivery. The edges end with points 2 and 3. A mark is assigned to each point representing the lower boundary of the route depending on the use or non-use of the given route.



Step 7

The branching is continued in any of the knots, 2 or 3, since their etiquettes have equal values. The calculation is continued in knot 2.

After applying the described procedure four (4) times, Table 6 is provided:

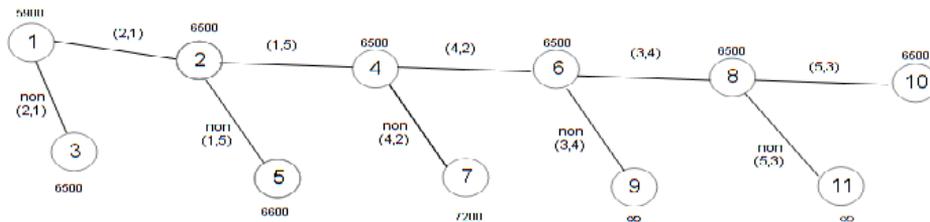
Table 6 – The end of the algorithm

addresses	3	4	r_i
3	∞	0	0
5	0	∞	0
c_j	0	0	

Source: authors

The complete branching tree is represented in Picture 1.

Picture 1. Branching Tree



Source: authors

It is concluded that 1 – 5 – 3 – 4 – 2 – 1 is the optimal route for the travelling salesman delivering to appointed addresses. Duration of the route is 6500 meters.

5. CONCLUSION

In this paper we have shown a way to solve the Travelling Salesman Problem by using data tables and the branch and bound method which have given the correct solution to the problem and have proven to be effective in up to 60 data entries. The method to solve the specific problem of package delivery to certain addresses knowing the exact distance between these addresses is used in this example.

By using this method, the optimal package delivery route as well as the duration of this route in meters is calculated. This research has demonstrated that a method to calculate optimal routes, used in this manner and without the use of computers and software packages, can be efficient.

In the context of competitive market it is important to rationalize every business segment by using mathematical methods such as this one. Rationalization by calculation of optimal routes of delivery is very simple to use and it reduces business costs considerably.

The Travelling Salesman Problem can be used widely in many human activities. One of the more important ones could be organizing the production and locating the most optimal sequence of operations and tasks. The sequence of implementing certain automated operations like drilling holes in printed circuit boards is one of the most important ways of optimizing the production process with the Travelling Salesman algorithm.

The branch and bound method is suitable for working with computer applications and it is considered to be one of the possible ways to encourage further exploration of this problem.

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Mirta Mataija¹

Mirjana Rakamarić Šegić²

Franciska Jozić³

Stručni rad

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535.242.65

RJEŠAVANJE PROBLEMA TRGOVAČKOG PUTNIKA KORIŠTENJEM METODE GRANANJA I OGRANIČAVANJA⁴

SAŽETAK

Cilj ovog rada je optimizirati dostavu paketa na slučajno odabrane adrese u Rijeci. Ovaj problem poznat je kao problem trgovačkog putnika, odnosno problem TSP-a i spada u grupu NP teških problema. U svrhu rješavanja zadatka u radu su definirani pojmovi Hamiltonova grafa, te Hamiltonova puta i ciklusa. Također je dana teorijska osnova metode grananja i ograđivanja. Na kraju rada ova je metoda korištena za rješavanje problema.

Ključne riječi: problem trgovačkog putnika, metoda grananja i ograđivanja, Hamiltonov put, Hamiltonov ciklus, NP potpuni problem, NP teški problemi

¹ Mr. sc., predavač, Veleučilište u Rijeci, Vukovarska 58, 51 000 Rijeka, Hrvatska. E-mail: mirta.mataija@veleri.hr

² Mr. sc., viši predavač, Veleučilište u Rijeci, Vukovarska 58, 51 000 Rijeka, Hrvatska. E-mail: mrakams@veleri.hr

³ Struč. spec. ing. traff, nastavnik, Prometna škola u Rijeci, Jože Vlahovića 10, Rijeka, Hrvatska. E-mail: franciskajozic@yahoo.com

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