

<p>ATMTKA 942</p>	<p>UDK 621.313.333.07 IFAC IA 2.1.4;3.1.1 Izvorni znanstveni članak</p> <p>AUTOMATIKA 44(3–4),113–122(2003) NEIZRAZITO ADAPTIVNO UPRAVLJANJE POGONOM S ASINKRONIM MOTOROM</p> <p><i>Mohamed Rachid Chekkouri, PhD Student, e-mail: chekkour@eel.upc.es</i> <i>Dr. Jordi Catal i L pez, Product Engineer, Control Techniques Iberia SA, e-mail: catala@eel.upc.es;</i> <i>Dr. Emiliano Aldabas Rubira, Lecturer, e-mail: aldabas@eel.upc.es</i> <i>Dr. Luis Romeral Martínez, Senior Lecturer, e-mail: Romeral@eel.upc.es;</i> <i>Electronic Engineering Department, Technical University of Catalonia, Campus Terrassa, TR2. C/Colom, no. 1, 08222. Terrassa, Catalonia, Spain, Phone number: +34 93 739 8194 Fax number: +34 93 739 8016</i></p> <p>Industrijske primjene sve više trebaju električne pogone s dobrim svojstvima pozicioniranja i regulacije tereta. To se može postići jedino adaptivnim načinom upravljanja, jer se uvjeti terećenja, momenti inercije kao i ostali parametri sustava mijenjaju tijekom gibanja. U članku je razvijen adaptivni regulator brzine vrtnje za izmjenični pogon s asinkronim motorom koji koristi jednostavan računski algoritam. Autori predlažu samopodešavajuće upravljanje zasnovano na neizrastitoj adaptaciji s nadzornog nivoa. Nadzorni algoritam neprestano prati stanje sustava i mijenja parametar K; standardnog PDF regulatora da bi ga adaptirao na promjene stanja u postrojenju. Neizrastita adaptivna strategija realizirana je bez poteškoća, sa svojstvom vrlo brzog učenja te vrlo dobrim svojstvima pozicioniranja i regulacije tereta. Analiza stabilnosti razvijenog regulatora također je napravljena, a eksperimentalni rezultati pokazuju robustnost predloženog algoritma pri uvjetima djelovanja poremećaja u obliku promjenljivog momenta tereta. <i>(Sl. 14, Tab. 1, Lit. 10 – original na engleskom)</i></p> <p><i>adaptivno upravljanje, pogoni podesive brzine vrtnje, neizrastita logika, upravljanje gibanjem, pogoni promjenljive brzine vrtnje</i></p> <p>ISSN 0005-1144 ATKAAF 44(3–4),113–122(2003)</p>		<p>ATMTKA 943</p> <p>UDK 621.313.282 IFAC IA 5.5.4 Prethodno priopćenje</p> <p>AUTOMATIKA 44(3–4),123–127(2003)</p> <p>PRIMJENA, PRORAČUN I ANALIZA DVOSTRUKO NAPAJANOG STATORA LINEARNOG MOTORA ZA ŽELJEZNIČKI NBP ISPITNI POLIGON (NBP – nova prijevozna tehnika Paderborn)</p> <p><i>M. Sc. Bo Yang, Prof. Dr. -Ing. Horst Grotstollen</i> <i>University of Paderborn, Institute of Power Electronics and Electrical Drives, FB 14/250</i> <i>Warburger Str. 100, 33098 Paderborn, Germany</i> <i>Email: {yang, grotstollen}@lea.upb.de http://wwwlea.upb.de</i></p> <p>Na sveučilištu Paderborn razvijen je novi mehatronički vučni pogon za željeznički transport. Vučni pogon je realiziran s linearnim motorom s dvostruko napajanim statorom, pri čemu se koristi postojeći mehanički sustav kotača s tračnicama. Statorski dio linearnog motora je postavljen između tračnica a rotorski ispod pomičnih vučnih kola. Modeliranje, proračun i analiza mehatroničkog vučnog pogona načinjeni su na prototipnom modelu u razmjeri 1:2,5. <i>(Sl. 5, Tab. 1, Lit. 6 – original na engleskom)</i></p> <p><i>Autori</i> <i>električni strojevi</i> <i>linearni pogoni</i> <i>modeliranje</i></p> <p>ISSN 0005-1144 ATKAAF 44(3–4),123–127(2003)</p>
<p>ATMTKA 944</p>	<p>UDK 621.311.1.072 IFAC IA 5.5.4 Stručni članak</p> <p>AUTOMATIKA 44(3–4),129–135(2003) UPRAVLJANJE STRUJOM TROFAZNIH PARALELNO SPOJENIH AKTIVNIH FILTARA S ČETIRI VODIČA</p> <p><i>Antonio Dell'Aquila, Professor; Agostino Lecci, PhD student</i> <i>Dipartimento di Elettrotecnica ed Elettronica, Politecnico di Bari, Via E. Orabona 4, 70125 Bari, Italy</i> <i>Phone: +39-080-5963.366/433, Fax: +39-080-5963.410</i> <i>dellaqui@poliba.it lecci@ieec.org http://dee.poliba.it</i></p> <p>Opisan je aktivni filter za kompenzaciju harmonijskog izobličenja, struje nultog sustava i jalove snage u trofaznim sustavima s četiri vodiča. Pozornost je usmjerena na upravljanje strujom da se postigne optimalno slijeđenje struje s pomoću konstantne frekvencije pobudnog signala. Djelotvornost predloženog upravljanja ispitana je simulacijom, gdje su harmonijsko zagađenje i neravnoteža, uzrokovani jakom distorzijom tereta, drastično reducirani. <i>(Sl. 11, Tab. 2, Lit. 18 – original na engleskom)</i></p> <p><i>Autori</i> <i>aktivni filteri</i> <i>neizrastita logika</i> <i>harmonici</i> <i>kvaliteta snage</i></p> <p>ISSN 0005-1144 ATKAAF 44(3–4),129–135(2003)</p>		<p>ATMTKA 945</p> <p>UDK 621.313.3:534.831 IFAC IA 4.2.2;5.5.4 Prethodno priopćenje</p> <p>AUTOMATIKA 44(3–4),137–145(2003) O EMISIJI BUKE IZ IZMJENIČNIH POGONA UPRAVLJANIH PULSNO-ŠIRINSKOM MODULACIJOM</p> <p><i>Dr. Eng. Stefan Laurentiu Capitaneanu</i> <i>STIE (Schneider Toshiba Inverter Europe); 33, rue André Blanchet, 27120 Pacy sur Eure, France</i> <i>Tel.: +33 232781947, Fax: +33 232781889</i></p> <p><i>Prof. Dr. Eng. Bernard de Fornel, Prof. Dr. Eng. Maurice Fadel</i> <i>LEEI (Laboratoire d'Electrotechnique et d'Electronique Industrielle UMR ENSEEIHT/CNRS)</i> <i>2, rue Camichel, B.P. 7122, 31071 Toulouse Cedex 7, France</i> <i>Tel.: +33 561588255, Tel.: +33 561588336, Fax: +33 561638875</i></p> <p><i>Dr. Eng. Fabrice Jadot</i> <i>STIE (Schneider Toshiba Inverter Europe); 33, rue André Blanchet, 27120 Pacy sur Eure, France</i> <i>Tel.: +33 232781495, Fax: +33 232781889</i></p> <p>U radu se izlaže eksperimentalna analiza buke emitirane iz izmjeničnih pogona upravljanih različitim postupcima pulsno-širinske modulacije (PWM). Nakon izlaganja utjecaja izbora PWM postupka na stupanj redukcije buke, uspoređeni su i interpretirani mjerni rezultati. Uzeto je u obzir pet kriterija: tip motora, snaga motora, brzina vrtnje, sklopna frekvencija i tip PWM postupka. <i>(Sl. 19, Lit. 10 – original na engleskom)</i></p> <p><i>Autori</i> <i>akustička i elektromagnetska buka</i> <i>strategije modulacije</i> <i>izmjenični strojevi</i> <i>pogoni s promjenljivom brzinom vrtnje</i></p> <p>ISSN 0005-1144 ATKAAF 44(3–4),137–145(2003)</p>

	<p>ATMTKA 946</p> <p style="text-align: right;">UDK 621.391.8:629.783 IFAC IA 5.8.3 Prethodno priopćenje</p> <p style="text-align: center;">AUTOMATIKA 44(3–4),147–153(2003)</p> <p style="text-align: center;">ANALIZA SATELITSKOG PROPAGACIJSKOG KANALA S POMOĆU »RAY-TRACING« SIMULACIJE</p> <p style="text-align: center;"><i>Mr. Sc. Zoran Blažević, Dr. Sc. Igor Zanchi, Red. Prof.; Mr. Sc. Ivan Marinović University of Split, Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split, Rudera Boškovića bb, 21000 Split, Croatia</i></p> <p>U članku je opisana analiza satelitskog propagacijskog kanala s pomoću metoda potvrđenih u znanstvenoj literaturi kao što su: »ray-tracing«, jedinstvena geometrijska teorija ogiba i Fourierova transformacija. Ti su postupci lako programabilni te stoga mogu poslužiti kao osnova analitičke programske podrške za razne radio kanale. Da bi oslikali njihove mogućnosti, odabran je primjer radio kanala Low-Earth Orbit satelita za različite kutove elevacije (ozračeno ili područje sjene) koji emitira na prijenosnoj frekvenciji 1625 MHz. U skladu s tim, prikazani su i analizirani dijagrami impulsnog odziva i Dopplerovi spektri. Može se zaključiti da se opisana simulacija može uspješno primijeniti pri analizi višestaznih radio kanala, posebno u slučajevima kada je potrebno odrediti temeljne parametre radio kanala poput koherentne širine pojasa ili koherentnog vremena.</p> <p><i>(Sl. 6, Lit. 12 – original na engleskom)</i></p> <p style="text-align: right;"><i>Autori</i></p> <p><i>satelitski propagacijski kanal »ray-tracing« jedinstvena geometrijska teorija ogiba impulsni odziv Dopplerov spektar</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3–4),147–153(2003)</p>		<p>ATMTKA 947</p> <p style="text-align: right;">UDK 681.586:532.696 IFAC IA 4.2.2 Izvorni znanstveni članak</p> <p style="text-align: center;">AUTOMATIKA 44(3–4),155–162(2003)</p> <p style="text-align: center;">ODREĐIVANJE POROZNOSTI PRIMJENOM STOHAŠTIČKE METODE</p> <p style="text-align: center;"><i>Assoc. Prof. Dr. Vojko Matko University of Maribor, Faculty of Electrical Engineering and Computer Science Smetanova 17, 2000 Maribor, Slovenia phone: +386-02-220-7111, E-mail: vojko.matko@uni-mb.si</i></p> <p>Razvijena je metoda za mjerenje poroznosti malih čvrstih uzoraka tla (približne mase od 1 g) s pomoću kapacitivno osjetljivog kristala. U radu je opisano novorazvijeni senzor i osjetljivost probe (ovisnost promjene frekvencije o volumenu). U nastavku je prikazana nova ideja pobude cijelog senzora stohastičkim ispitnim signalima kao nova metoda mjerenja poroznosti. Ona uključuje utjecaj ispitnog signala na težinsku funkciju mjerne nesigurnosti. Prikazani su eksperimentalni rezultati mjerenja poroznosti vulkanskih stijena. Kod mjerenja poroznosti dobivena je mjerna nesigurnost manja od 0,1 % u temperaturnom području od 10 do 30 °C.</p> <p><i>(Sl. 9, Lit. 33 – original na engleskom)</i></p> <p style="text-align: right;"><i>Autor</i></p> <p><i>poroznost vulkanska stijena kapacitivno osjetljivi kristal stohastička metoda</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3–4),155–162(2003)</p>
	<p>ATMTKA 948</p> <p style="text-align: right;">UDK 681.518.5 IFAC IA 2.5 Izvorni znanstveni članak</p> <p style="text-align: center;">AUTOMATIKA 44(3–4),163–181(2003)</p> <p style="text-align: center;">KLIZNI REŽIMI U DISKRETNIM SUSTAVIMA UPRAVLJANJA</p> <p style="text-align: center;"><i>Prof. Dr. Asif Šabanović, Professor Sabanci University, Faculty of Engineering and Natural Sciences, 34956 Istanbul-Tuzla, Turkey Tel +90 216 483 9502, Fax +90 216 483 9550, e-mail: asif@sabanciuniv.edu</i></p> <p style="text-align: center;"><i>Dr. Nadira Šabanović Sabanci University, Faculty of Engineering and Natural Sciences, 34956 Istanbul-Tuzla, Turkey Tel +90 216 483 9542, Fax +90 216 483 9550, e-mail: nadira@sabanciuniv.edu</i></p> <p style="text-align: center;"><i>Karel Jezernik, Professor University of Maribor – FERI, Maribor, Slovenia Tel +386 2 220 7500, e-mail: karel.jezernik@uni-mb.si</i></p> <p>Primjena algoritama kliznih režima rada, koji spadaju u grupu algoritama s promjenljivom strukturom upravljanja, može u diskretnim sustavima upravljanja rezultirati neželjenim oscilacijama regulirane varijable. U svrhu sprječavanja ovih oscilacija u radu je predložen jedan novi pristup u sustavu upravljanja s kliznim režimom rada. Predloženim postupkom eliminira se računanje ekvivalentnog upravljanja, smanjuje utjecaj neodređenosti sustava i značajno smanjuju oscilacije izlazne regulirane varijable. Postupak je jednako primjenljiv na linearne i na nelinearne sustave. On omogućuje sintezu sustava bez transformacije u diskretnu formu (z-područje). Gornja granica vrijednosti vremena uzorkovanja određena je iz zahtjeva za ograničenjem promjene funkcije klizanja unutar vremena intervala uzorkovanja. Analiziran je sustav s estimatorom stanja. Kao pokazatelj kvalitete predloženog algoritma prikazani su simulacijski i eksperimentalni rezultati ispitivanja.</p> <p><i>(Sl. 9, Lit. 16 – original na engleskom)</i></p> <p style="text-align: right;"><i>Autori</i></p> <p><i>vremenski diskretni sustav, linearni sustav sinteza po Ljapunovu, klizni režim, sustavi s promjenljivom strukturom</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3–4),163–181(2003)</p>		

<p>ATMTKA 947</p> <p style="text-align: right;">UDK 681.586:532.696 IFAC IA 4.2.2 Original scientific paper</p> <p style="text-align: center;">AUTOMATIKA 44(3-4),155-162(2003)</p> <p style="text-align: center;">POROSITY DETERMINATION BY USING STOCHASTICS METHOD</p> <p style="text-align: center;"><i>Assoc. Prof. Dr. Vojko Matko</i> <i>University of Maribor, Faculty of Electrical Engineering and Computer Science</i> <i>Smetanova 17, 2000 Maribor, Slovenia</i> <i>phone: +386-02-220-7111, E-mail: vojko.matko@uni-mb.si</i></p> <p>In response to a need for a more accurate porosity measuring method for small solid samples (approximately 1 g in mass) the porosity measurement sensor using the sensitive capacitive-dependent crystal was developed. This paper presents the new sensor and the probe sensitivity (dependence of df on the volume). In addition, the new idea of excitation of the entire sensor with stochastic test signals is described, and the porosity measuring method is provided. The latter includes the influence of test signals on the weighting function uncertainty. The experimental results of the porosity determination in volcanic rock samples are presented. The uncertainty of the porosity measurement is less than 0.1 % ($T_{emp} = 10-30$ C).</p> <p><i>(Fig. 9, Ref. 33 – original in english)</i></p> <p><i>porosity</i> <i>volcanic rock</i> <i>capacitive-dependent crystal</i> <i>stochastics method</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3-4),155-162(2003)</p>			<p>ATMTKA 946</p> <p style="text-align: right;">UDK 621.391.8:629.783 IFAC IA 5.8.3 Preliminary communication</p> <p style="text-align: center;">AUTOMATIKA 44(3-4),147-153(2003)</p> <p style="text-align: center;">SATELLITE PROPAGATION CHANNEL ANALYSIS VIA RAY-TRACING SIMULATION</p> <p style="text-align: center;"><i>Mr. Sc. Zoran Blažević; Dr. Sc. Igor Zanchi, Red. Prof.; Mr. Sc. Ivan Marinović</i> <i>University of Split, Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture</i> <i>Split, Rudera Boškovića bb, 21000 Split, Croatia</i></p> <p>The paper deals with a satellite propagation channel analysis via powerful methods such as ray-tracing, uniform geometrical theory of diffraction and Fourier Transform, already confirmed in various scientific literature. These procedures are easily programmable, and thus can be used as basis for analysing software of various radio channels. In order to present their suitability, an example of radio channel of Low-Earth Orbit satellite that emits at central frequency 1625 MHz at various elevation angles (illuminated and shadow zone) is exploited. Accordingly, the diagrams of impulse response and Doppler power spectra are shown and commented. It can be concluded that presented simulation can be successfully applied for multipath radio channel analysis, especially when fundamental channel parameters such as coherence bandwidth or coherence time are to be determined.</p> <p><i>(Fig. 6, Ref. 12 – original in english)</i></p> <p><i>satellite propagation channel</i> <i>ray-tracing</i> <i>uniform geometrical theory of diffraction</i> <i>impulse response</i> <i>Doppler spectrum</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3-4),147-153(2003)</p>
			<p>ATMTKA 948</p> <p style="text-align: right;">UDK 681.518.5 IFAC IA 2.5 Original scientific paper</p> <p style="text-align: center;">AUTOMATIKA 44(3-4),163-181(2003)</p> <p style="text-align: center;">SLIDING MODES IN SAMPLED-DATA SYSTEMS</p> <p style="text-align: center;"><i>Prof. Dr. Asif Šabanović, Professor</i> <i>Sabanci University, Faculty of Engineering and Natural Sciences, 34956 Istanbul-Tuzla, Turkey</i> <i>Tel +90 216 483 9502, Fax +90 216 483 9550, e-mail: asif@sabanciuniv.edu</i></p> <p style="text-align: center;"><i>Dr. Nadira Šabanović</i> <i>Sabanci University, Faculty of Engineering and Natural Sciences, 34956 Istanbul-Tuzla, Turkey</i> <i>Tel +90 216 483 9542, Fax +90 216 483 9550, e-mail: nadira@sabanciuniv.edu</i></p> <p style="text-align: center;"><i>Karel Jezernik, Professor</i> <i>University of Maribor – FERI, Maribor, Slovenia</i> <i>Tel +386 2 220 7500, e-mail: karel.jezernik@uni-mb.si</i></p> <p>The sliding mode application in discrete-time systems can result in unwanted oscillations of the controlled variable (so called chattering). To avoid above-mentioned oscillations a new approach in the design of sliding mode control is proposed in this paper. In the proposed approach the calculation of the equivalent control is not necessary while the influence of the system uncertainty and chattering are reduced. The proposed method is applicable to linear as well as nonlinear systems. It allows the design of the control without transformation of the system description to the discrete-time form (z-domain). Upper bound of the sampling time is determined from the switching function changes during the sampling period. The systems with state observers are analyzed. Experimental and simulation results are presented to clarify the design procedure and the features of the proposed algorithm.</p> <p><i>(Fig. 9, Ref. 16 – original in english)</i></p> <p><i>discrete-time systems, linear systems</i> <i>Liapunov design, nonlinear systems</i> <i>sliding mode, variable structure systems</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3-4),163-181(2003)</p>

<p>ATMTKA 943</p> <p style="text-align: right;">UDK 621.313.282 IFAC IA 5.5.4 Preliminary communication</p> <p style="text-align: center;">AUTOMATIKA 44(3-4),123-127(2003)</p> <p style="text-align: center;">APPLICATION, CALCULATION AND ANALYSIS OF DOUBLY FED LONG STATOR LINEAR MOTOR FOR NBP TEST TRACK</p> <p style="text-align: center;"><i>M. Sc. Bo Yang, Prof. Dr. -Ing. Horst Grotstollen</i> University of Paderborn, Institute of Power Electronics and Electrical Drives, FB 14/250 Warburger Str. 100, 33098 Paderborn, Germany Email: {yang, grotstollen}@lea.upb.de http://www.lea.upb.de</p> <p>At the University of Paderborn a novel mechatronic railway system is developed, whose shuttles are guided by ordinary wheels and rails and driven by a doubly fed linear motor automatically. The primary (stator) is installed between the rails, and the secondary (rotor) fixed below the undercarriage. In this paper the modeling, calculation and analysis of a prototype of such a linear motor on a scale 1:2.5 are described in detail.</p> <p>(Fig. 5, Tab. 1, Ref. 6 – original in english)</p> <p style="text-align: right;"><i>Authors</i></p> <p><i>electrical machines linear drives modeling</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3-4),123-127(2003)</p>			<p>ATMTKA 942</p> <p style="text-align: right;">UDK 621.313.333.07 IFAC IA 2.1.4;3.1.1 Original scientific paper</p> <p style="text-align: center;">AUTOMATIKA 44(3-4),113-122(2003)</p> <p style="text-align: center;">FUZZY ADAPTIVE CONTROL OF AN INDUCTION MOTOR DRIVE</p> <p style="text-align: center;"><i>Mohamed Rachid Chekkouri, PhD Student, e-mail: chekkour@eel.upc.es</i> <i>Dr. Jordi Catal i Lopez, Product Engineer, Control Techniques Iberia SA, e-mail: catala@eel.upc.es;</i> <i>Dr. Emiliano Aldabas Rubira, Lecturer, e-mail: aldabas@eel.upc.es</i> <i>Dr. Luis Romeral Martínez, Senior Lecturer, e-mail: Romeral@eel.upc.es;</i> <i>Electronic Engineering Department, Technical University of Catalonia, Campus Terrassa, TR2. C/Colom, no. 1, 08222. Terrassa, Catalonia, Spain, Phone number: +34 93 739 8194 Fax number: +34 93 739 8016</i></p> <p>Industrial applications increasingly require electric drives with good position command tracking and load regulation responses. These conditions can only be achieved by adaptive-type control because of the loading conditions, inertias and system parameters all change during the motion. For this paper an Adaptive Speed Controller for AC drives with a very low computational algorithm was developed. The authors propose self-tuning control based on a supervisory fuzzy adaptation. The supervisor continuously monitors the status of the system and changes the K_f parameter of a standard PDF controller to adapt it to the plant's evolution. The fuzzy logic adaptive strategy was readily implemented and showed very fast learning features and very good tracking and regulation characteristics. The stability of the controller developed was also analysed, and experimental results demonstrated the robustness of the suggested algorithm in contending with varying load and torque disturbance.</p> <p>(Fig. 14, Tab. 1, Ref. 10 – original in english)</p> <p style="text-align: right;"><i>Authors</i></p> <p><i>adaptive control, adjustable speed drives fuzzy logic, motion control, variable speed drives</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3-4),113-122(2003)</p>
<p>ATMTKA 945</p> <p style="text-align: right;">UDK 621.313.3:534.831 IFAC IA 4.2.2;5.5.4 Preliminary communication</p> <p style="text-align: center;">AUTOMATIKA 44(3-4),137-145(2003)</p> <p style="text-align: center;">ON THE ACOUSTIC NOISE RADIATED BY PWM AC MOTOR DRIVES</p> <p style="text-align: center;"><i>Dr. Eng. Stefan Laurentiu Capitaneanu</i> STIE (Schneider Toshiba Inverter Europe); 33, rue André Blanchet, 27120 Pacy sur Eure, France Tel.: +33 232781947, Fax: +33 232781889</p> <p style="text-align: center;"><i>Prof. Dr. Eng. Bernard de Fornel, Prof. Dr. Eng. Maurice Fadel</i> LEEI (Laboratoire d'Electrotechnique et d'Electronique Industrielle UMR ENSEIHT/CNRS) 2, rue Camichel, B.P. 7122, 31071 Toulouse Cedex 7, France Tel.: +33 561588255, Tel.: +33 561588336, Fax: +33 561638875</p> <p style="text-align: center;"><i>Dr. Eng. Fabrice Jadot</i> STIE (Schneider Toshiba Inverter Europe); 33, rue André Blanchet, 27120 Pacy sur Eure, France Tel.: +33 232781495, Fax: +33 232781889</p> <p>The paper presents and analyses the experimental acoustic noise of AC motors controlled by drives using different PWM techniques. After a discussion upon PWM methods concerning noise reduction, measure based comparisons are interpreted. Five criteria are taken into account: motor type, motor power, rotor speed, switching frequency and PWM method.</p> <p>(Fig. 19, Ref. 10 – original in english)</p> <p style="text-align: right;"><i>Authors</i></p> <p><i>noise acoustical and electromagnetic modulation strategies AC machines variable speed drives</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3-4),137-145(2003)</p>			<p>ATMTKA 944</p> <p style="text-align: right;">UDK 621.311.1.072 IFAC IA 5.5.4 Professional paper</p> <p style="text-align: center;">AUTOMATIKA 44(3-4),129-135(2003)</p> <p style="text-align: center;">A CURRENT CONTROL FOR THREE-PHASE FOUR-WIRE SHUNT ACTIVE FILTERS</p> <p style="text-align: center;"><i>Antonio Dell'Aquila, Professor; Agostino Lecci, PhD student</i> Dipartimento di Elettrotecnica ed Elettronica, Politecnico di Bari, Via E. Orabona 4, 70125 Bari, Italy Phone: +39-080-5963.366/433, Fax: +39-080-5963.410 dellaqui@poliba.it lecci@ieee.org http://dee.poliba.it</p> <p>An active filter has been proposed to compensate for harmonic distortion, line neutral current and reactive power in three-phase four-wire systems. The focus is concentrated on current control in order to achieve optimum current tracking by means of fixed frequency driving signals. The effectiveness of proposed control was proved in simulations where the harmonic pollution and imbalance caused by a highly distorting load have been drastically reduced.</p> <p>(Fig. 11, Tab. 2, Ref. 18 – original in english)</p> <p style="text-align: right;"><i>Authors</i></p> <p><i>active filters fuzzy logic harmonics power quality</i></p> <p style="text-align: right;">ISSN 0005-1144 ATKAAF 44(3-4),129-135(2003)</p>