UNIT-SPHERE PRESERVING MAPPINGS

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ABSTRACT. We prove that if a one-to-one mapping $f : \mathbb{R}^n \to \mathbb{R}^n$ $(n \geq 2)$ preserves the unit n-1 spheres (S^{n-1}) , then f is a linear isometry up to translation.

1. INTRODUCTION

Let X and Y be normed spaces. A mapping $f:X\to Y$ is called an isometry if f satisfies the equality

$$||f(x) - f(y)|| = ||x - y||$$

for all $x, y \in X$. A distance r > 0 is said to be preserved (conservative) by a mapping $f : X \to Y$ if

$$||f(x) - f(y)|| = r$$
 for all $x, y \in X$ with $||x - y|| = r$.

If f is an isometry, then every distance r > 0 is conservative by f, and conversely. We can now raise a question whether each mapping that preserves certain distances is an isometry. Indeed, A. D. Aleksandrov [1] had raised a question whether a mapping $f : X \to X$ preserving a distance r > 0 is an isometry, which is now known to us as the Aleksandrov problem. Without loss of generality, we may assume r = 1 when X is a normed space (see [15]).

F. S. Beckman and D. A. Quarles [2] solved the Aleksandrov problem for finite-dimensional real Euclidean spaces $X = \mathbb{R}^n$ (see also [3, 4, 5, 6, 7, 8, 10, 11, 12, 13, 14, 16, 17, 18, 19]):

 $^{^{*}{\}rm The}$ first author was supported by Korea Research Foundation Grant (KRF-2003-015-C00023).



²⁰⁰⁰ Mathematics Subject Classification. 51K05.

Key words and phrases. Isometry, unit-circle preserving mapping.

THEOREM 1.1 (Theorem of Beckman and Quarles). If a mapping $f : \mathbb{R}^n \to \mathbb{R}^n \ (2 \le n < \infty)$ preserves a distance r > 0, then f is a linear isometry up to translation.

It seems to be interesting to investigate whether the 'distance r > 0' in the above theorem can be replaced by some properties characterized by 'geometrical figures' without loss of its validity.

In [9], the first author proved that if a one-to-one mapping $f : \mathbb{R}^n \to \mathbb{R}^n$ $(n \geq 2)$ maps the periphery of every regular triangle (quadrilateral or hexagon) of side length a > 0 onto the periphery of a figure of same type with side length b > 0, then there exists a linear isometry $I : \mathbb{R}^n \to \mathbb{R}^n$ up to translation such that

$$f(x) = (b/a)I(x).$$

In this note, we show further that if a one-to-one mapping $f : \mathbb{R}^n \to \mathbb{R}^n$ $(n \ge 2)$ maps every unit n-1 sphere (S^{n-1}) onto a unit n-1 sphere (S^{n-1}) , then f is a linear isometry up to translation.

2. Main theorem

Now, let us prove our main theorem.

THEOREM 2.1. If a one-to-one mapping $f : \mathbb{R}^n \to \mathbb{R}^n$ $(n \ge 2)$ maps every unit n-1 sphere onto a unit n-1 sphere, then f is a linear isometry up to translation.

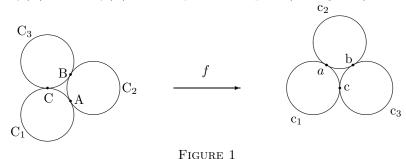
PROOF. Assume $n \ge 3$ first. We show f preserves the distance 2. Assume $T_1, T_2 \in \mathbb{R}^n$ and $d(T_1, T_2) = 1$. Without loss of generality assume that $T_1 = ((1/\sqrt{2}), (1/\sqrt{2}), 0, \dots, 0)$ and $T_2 = (0, (1/\sqrt{2}), (1/\sqrt{2}), 0, \dots, 0)$. Define S_1, \dots, S_n, S_{n+1} to be the unit n-1 spheres (S^{n-1}) centered at $A_1 = (\sqrt{2}, 0, \dots, 0), A_2 = (0, \sqrt{2}, 0, \dots, 0), \dots, A_n = (0, \dots, 0, \sqrt{2}),$ and $A_{n+1} = (x, x, \dots, x)$ respectively, where x is the unique negative real number satisfying $d(A_i, A_{n+1}) = 2$, $i = 1, \dots, n$. The S_i 's are all unit n-1 spheres such that any pair of these spheres meet each other at exactly one point. Then the same must be true for their image spheres D_1, \dots, D_n, D_{n+1} . Denote the centers of these image spheres by B_1, \dots, B_n, B_{n+1} . Because any pair of these spheres intersect each other at exactly one point, we have $d(B_i, B_j) = 2$ whenever $i \neq j$.

Now if we are given two sets in \mathbb{R}^n , each of which contain n + 1 points whose mutual distances are all equal to 2, then there is an isometry $\phi : \mathbb{R}^n \to \mathbb{R}^n$ with $\phi(B_i) = A_i$, and consequently $(\phi \circ f)(S_i) = S_i$, $i = 1, \ldots, n + 1$. Since $S_1 \cap S_2 = \{T_1\}$ and $S_2 \cap S_3 = \{T_2\}$, we have necessarily $(\phi \circ f)(T_1) = T_1$ and $(\phi \circ f)(T_2) = T_2$. Thus $d(f(T_1), f(T_2)) = 1$, as desired.

For n = 2, consider two points A and B in \mathbb{R}^2 which are separated from each other by the unit distance. Then we can draw three unit circles C_1, C_2, C_3 such that any two of them touch each other at one point as in Figure 1. If

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we call $c_i = f(C_i)$ (i = 1, 2, 3), then we get the three contact points a, b, c which form the three vertices of a regular triangle with unit distance. Now since f(A) = a and f(B) = b, the proof is complete (see Figure 1).



ACKNOWLEDGEMENTS.

The authors express their cordial thanks to the referee for his valuable suggestions to shorten the proof of the main theorem.

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Received: 15.09.2003. Revised: 07.11.2003.

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