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WRINKLING PREDICTION IN DEEP DRAWING BY USING RESPONSE SURFACE METHODOLOGY AND ARTIFICIAL NEURAL NETWORK

Summary

The objective of this study is to predict influences of tooling parameters such as die and punch radius, blank holder force and friction coefficient between the die and the blank surfaces in a deep drawing process on the wrinkling height in aluminium AA5754 by using the response surface methodology (RSM) and an artificial neural network (ANN). The 3D finite element method (FEM), i.e. the Abaqus software, is employed to model the deep drawing process. In order to investigate the accuracy of this model, the results are compared with experimental results. The data derived from the FEM are used for modelling the RSM and training an ANN. Finally, the RSM and ANN outputs are compared so as to select the best model. The results of the two methods are promising and it is found that the ANN results are more accurate than the RSM results.

Key words: ANN, deep drawing, FEM, RSM, wrinkling

1. Introduction

The deep drawing process is a significant process in sheet metal forming which is extensively used in industry for converting sheet metal blank to hollow parts without seem at high production rates. One of the predominant and deleterious effects in deep drawing is wrinkling which is induced by plastic instability. The effect of various factors that lead to wrinkling occurrence are: the blank holder force, the geometrical parameters of the die such as die radius and punch radius, the friction coefficient between die and workpiece, the workpiece geometry, the mechanical properties of material etc. Since the wrinkling height is a determinative factor in the evaluation of products, the prediction of this parameter before the process is carried out can prevent material wastage. Methods such as RSM and ANN have particular computational properties that make them suited for particular applications such as prediction. Nowadays, most studies related to the deep drawing process investigate the optimization in order to reduce the wrinkling height. A comprehensive literature review has been done on various aspects of the deep drawing process in the field of prediction and wrinkling (Table 1).

 Table 1
 Literature review

Investigator No.	Material	Technique	Input parameters	Output response	Finding of the study
1. Singh and Gupta (2010) [1]	IF Steel	SVR Modelling, ANN and FEM	Design, Process and Material	Thickness	The SVR worked significantly well and predicted a large portion of thickness strains correctly, especially in the wall region of the drawn cup.
2. Saxena and	Aluminium	Bifurcation	Material	Wrinkling	An increase in the blank holder pressure or
Dixit (2010) [2]	(AA2090- T3, AA6111- T4)	Criterion	Properties and Tool Dimension		the sheet thickness delays the onset of wrinkling. The maximum cup height at the onset of wrinkling increases with an increase in the die profile radius or punch profile radius. The sheet anisotropy, in general, delays the onset of wrinkling.
3. Morovvati et al. (2010) [3]	Aluminium (Al3105, Al1100) and Steel (SUS304)	Analytical Method (energy method) and FEM	Material properties of two layer sheets	Wrinkling	The minimum required blank holder force to prevent wrinkling in the case of A.I. lay-ups is higher than the one in the case of S.I. lay-ups. The forming force of A.I. lay-ups is greater than the one of S.I. lay-ups. The resultant yield stress of two-layer sheets is a function of the yield stress of their components.
4. Kim et al. (2001) [4]	Aluminium (A6111-T4)	Bifurcation Criterion	Tool Dimensions	Wrinkling	As the ratio of the punch increases the wrinkling initiation is retarded and fracture takes place earlier near to the major axis.
5. Correia and Ferron (2004) [5]	Mild Steel	Bifurcation Criterion and FEM	Plastic Anisotropy Of Material	Wrinkling	The numerical predictions are in good agreement with experiments. They also compare reasonably well with the analytical predictions of wrinkling, concerning both the number of wrinkles and their angular location relative to the orthotropic axes of the material.
6. Zeng and Mahdavian (1998) [6]	Aluminium	Theoretical Model (Equilibrium Moment)	Temperature	Wrinkling	The results of the theoretical solution are compared with the experimental results at ambient and elevated temperatures and good agreement is found.
7. Khelifa and Oudjene (2008) [7]	Steel	Plasticity Damage Model and FEM	Punch Travel and Punch Stroke	Damage	The developed model allows for prediction of damage in the workpiece during stamping or forming. This model also predicts the elastic, plastic and hardening behaviors neglected in approaches which do not use a coupled technique.
8. Sheng et al. (2004) [8]	Steel	Adaptive FEM	Punch Stroke	Blank Holder Force	Such a blank holder force profile can improve the formability of the conical cup drawing process, i.e. by increasing (a) the failure-free drawing depth and (b) the uniformity of the wall thinning distribution. The proposed method can be further improved to determine nearly optimum blank holder force profiles for drawing more complex parts, such as rectangular pan or nonsymmetric automotive stampings.
9. Zein et al. (2014) [9]	Mild steel	FEM	Friction and Tool Dimensions	Spring Back and Thinning	The die shoulder radius is recommended to be about 10 times sheet thickness. The punch nose radius is recommended to be greater than 4 times sheet thickness. The thicker sheet metal is softer due to its increased volume, which increases the thinning and reducing of the spring back in sheet metal. The fluid lubricant is more suitable for the punch/blank interface to reduce the thinning

Investigator No.	Material	Technique	Input parameters	Output response	Finding of the study
					and the spring back in the cup.
10. Padmanabhan et al. (2007) [10]	Stainless Steel	FEM and Taguchi Method	Die Radius, Friction and Blank Holder Force	Deep Drawing Process	The die radius (89.2%) has major influence on the deep-drawing process, followed by the friction coefficient (6.3%) and the blank holder force (4.5%).
11. Gusel et.al. (2015) [11]	Copper Alloy	Genetic programming and regression analysis	Drawing speed, die angle, rod dimension	Elongation	High precise models developed through GP approach can provide results with less experiments/simulations. GP models have lower deviation compared to regression models.

It is evident from the literature review that almost nothing has been reported on the prediction of the effect of the parameters such as die radius, punch radius, blank holder force and friction coefficient on wrinkling in aluminium AA5754 by RSM and ANN. Fig. 1 shows a 2D schematic of the deep drawing process including these effective parameters.

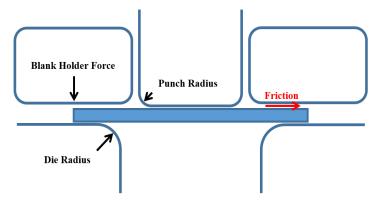


Fig. 1 2D schematic of deep drawing process including effective parameters

2. Methodology

In order to predict the wrinkling height, the following steps are carried out:

- Design of Experiment (DOE) is used for designing tests.
- The designed tests are done by applying the FEM by means of the Abaqus software.
- The FEM results are prepared to specify inputs for RSM and ANN to predict the wrinkling height.
- The results of RSM and ANN are compared with the FEM outputs to select the best method for prediction.

2.1 Design of Experiment

The aim of this study is to predict the wrinkling height by changing four variables including die radius (R_D) , punch radius (R_P) , friction coefficient (μ) and blank holder force (BHF) that have the strongest effect on the wrinkling height (WH). In the previous study by these authors the influence of these variables was investigated [12], so in this paper, the effective range of each parameter is considered in the design of the tests. For each factor five levels are defined as summarized in Table 2. The upper level of a factor is coded as +2, the center level as 0, and the lower level as -2.

Table 2 Factors and their levels

Factor	Notation	Unit	Factor levels				
			-2	-1	0	1	2
Die radius	R_D	mm	14	15	16	17	18
Punch radius	R_P	mm	16	18	20	22	24
Friction coefficient	μ	-	0.04	0.06	0.08	0.10	0.12
Blank holder force	BHF	MPa	0.80	0.95	1.10	1.25	1.40

The process of selecting tests is known as the design of experiment (DOE). In this paper, the central composite design (CCD) is employed for training data. This method is rotatable and created easily from 2^k factorials. The CCD for four parameters includes 25 samples that consist of 16 corner points, 8 axial points and 1 centre point. Table 3 shows the data set in a coded form. These data are used by the Abaqus software so as to specify *WH*.

2.2 FEM Modelling

In the previous study by the authors, a 3D deep drawing process has been simulated using a commercial finite element code, Abaqus, and verified by experimental tests. The dimensions of blank, square cup and hydraulic press are considered as specified in the mentioned study [12] and Al 5754, whose properties are presented in Fig. 2, is chosen for the blank.

EM Characteristics	Type &							
Blank element type	S4R							2000
Blank element number	6716				NP.			
Blank holder type	R3D4			A STATE OF THE PARTY OF THE PAR				
Blank holder element number	1683							
Punch element type R3D4								
Punch element number	3051		3D Numer	ical Mode	el of Dee	p Draw	ing Process an	d Blank
Die element type	R3D4							
Die element number	5945							7
Blank Mechanical Prope	rties	Value						
Specific gravity (Kg/m ³)		2643		Mag				
Poisson ratio		0.33			J			
Young modulus (GPa)		70.23	a. minimum <i>WH</i> b. maximum <i>WH</i>					
Strength coefficient (MPa))	416.5						
R 0		0.705	Trial no.	Leve	ls of inp	ut fact	ors (coded)	FEM
R 45		0.765		R_D	R_P	μ	BHF	WH
R 90		0.906	4 (a)	0	-2	0	0	1.39
Deformation hardening coefficient		0.2939	12 (b)	2	0	0	0	2.15

Fig. 2 FEM modelling

Fig. 2 shows the numerical model created by the Abaqus software. The output values obtained from the 3D simulation of the deep drawing process with FEM are presented in Table 3.

Table 3 Design matrix for data set in coded form along with FEM results

Trial no.	Levels of input factors (coded)			FEM	Trial no.	Leve (cod	ctors	FEM			
	R_D	R_P	μ	BHF	WH		R_D	R_P	μ	BHF	WH
1	0	0	0	0	1.71	14	-1	1	1	-1	1.79
2	1	1	-1	-1	2.01	15	0	0	0	-2	1.76
3	0	2	0	0	2.05	16	0	0	0	2	1.64
4	0	-2	0	0	1.39	17	0	0	-2	0	1.75
5	1	-1	1	1	1.62	18	-1	1	-1	1	1.76
6	1	-1	-1	1	1.67	19	1	1	-1	1	1.86
7	-1	1	1	1	1.69	20	0	0	2	0	1.56
8	1	1	1	1	1.84	21	-1	-1	1	1	1.43
9	-1	-1	1	-1	1.44	22	-1	1	-1	-1	1.85
10	1	1	1	-1	1.95	23	-1	-1	-1	-1	1.49
11	-1	-1	-1	1	1.48	24	1	-1	1	-1	1.69
12	2	0	0	0	2.15	25	1	-1	-1	-1	1.72
13	-2	0	0	0	1.43						

2.3 RSM Modelling

RSM is a combination of mathematical and statistical methods used in an empirical study of relationships and optimization, where several independent variables influence a dependent variable or response. RSM is a model building technique based on the statistical DOE and least square error fitting [13]. RSM, which creates polynomial models for the available data, is given in Eq. 1.

$$Y_{u} = b_{0} + \sum_{i=1}^{k} b_{i} X_{i} + \sum_{i=1}^{k} b_{ii} X_{i}^{2} + \sum_{j>k}^{k} b_{ij} X_{i} X_{j}$$

$$\tag{1}$$

In this equation, Y_u is the output parameter, b_0 is the constant coefficient, b_{ii} is the second order coefficient and b_{ij} is the interaction coefficient. In Fig. 3, WH versus input parameters is illustrated as it is indicated, WH increases with an increase in R_D and R_P and decreases with an increase in μ and BHF. The model fitted to the data is given in Eq. 2

$$WH = -2.90 + 2.71BHF + 0.305R_P - 0.187R_D + 1.8\mu$$

$$-0.199BHF^2 + 0.00018R_P^2 + 0.0174R_D^2 - 38.4\mu^2$$

$$-0.0707BHF * R_P - 0.069BHF * R_D + 0.12BHF * \mu$$

$$-0.00975R_P * R_D - 0.060R_P * \mu + 0.236R_D * \mu$$
(2)

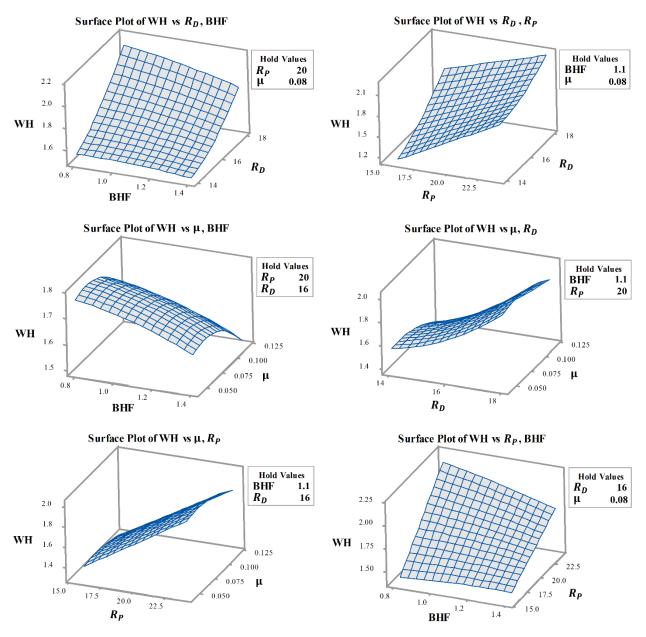


Fig. 3 WH versus input parameters

A sensitivity analysis is run to further validate each model and examine the contribution of an input variable to the output for each individual case in the training data. As Fig. 4 shows, R_P and μ have the most and least influence on the output, respectively. Furthermore, the sensitivity analysis displays that by increasing BHF and μ , WH decreases and by increasing R_P and R_D , WH grows.

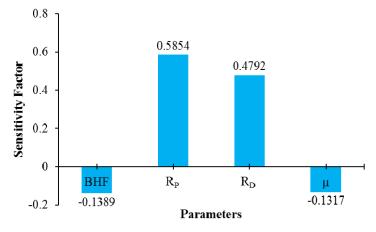


Fig. 4 RSM sensitivity analysis

Finally, Table 4 is presented with the aim of comparing the RSM to the FEM results based on 25 input data.

Table 4	Comparison	between	RSM	and	FEM	results
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Trial no.	rial no. WH		Error	Trial no.	WH	WH		
	FEM	RSM			FEM	RSM		
1	1.71	1.70	0.01	14	1.79	1.75	0.0	
2	2.01	2.04	-0.03	15	1.76	1.75	0.0	
3	2.05	2.00	0.05	16	1.64	1.61	0.0	
4	1.39	1.41	-0.02	17	1.75	1.70	0.0	
5	1.62	1.64	-0.02	18	1.76	1.74	0.0	
6	1.67	1.69	-0.02	19	1.86	1.91	-0.	
7	1.69	1.66	0.03	20	1.56	1.57	-0	
8	1.84	1.85	-0.01	21	1.43	1.37	0.0	
9	1.44	1.38	0.06	22	1.85	1.83	0.0	
10	1.95	1.98	-0.03	23	1.49	1.45	0.0	
11	1.48	1.44	0.04	24	1.69	1.69	0.0	
12	2.15	2.00	0.15	25	1.72	1.74	-0	
13	1.43	1.53	-0.10	<u></u>				

2.4 ANN Modelling

A neural network is a parallel processing architecture consisting of a large number of interconnected processors, called neurons, organized in layers [14]. The performance of a neural network depends mainly on its weights of connection. In general, each neuron can be connected with all other neurons. For manufacturing processes where no satisfactory analytic model exists or a low order empirical polynomial model is inappropriate, neural networks offer a good alternative approach [15].

Recently, many different neural network models have been developed. They include Perceptron, Hopfield and Hamming Network. Various types of algorithms used for training ANNs include Backpropagation, Delta Learning Rule, Hebb Learning Rule and Bayesian Regularization Algorithm [16]. There are several transfer functions such as Hardlim, Purelin and Logsig function utilized in neural network models.

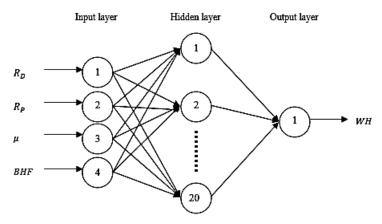


Fig. 5 The architecture of ANN for WH models

In this paper, an ANN is also considered in order to assess the best method for the prediction of WH. The neural network that is employed is the multilayer perceptron that learned by using the Bayesian Regularization Algorithm. The data that were used for training

and testing the ANN are the same as the data used for RSM (the number of training and testing data is 25 and 5, respectively). Fig. 5 shows the architecture of the neural network utilized for the prediction of WH. As Fig. 5 shows, the hidden layer has 20 neurons with the Logsig function. The function of the output layer, Hardlim, is taken into account. The learning factors of the training network are presented in Table 5.

Table 5 Learning factors

Learning factors	Value
Learning rate (η)	0.05
Momentum constant	0.9
Learning rate increment	1.1
Maximum number of epochs	3000
Target for MSE	0.0001

The principal steps in the training process are given below:

- 1. Initialize all of the weights of the links to random values.
- 2. Present the input-desired output patterns one by one, updating the weights each time using Eq. 3.

$$w_{ji(n+1)} = w_{ji(n)} + \eta \delta_{pj} o_{pi} + \alpha \Delta w_{ji(n)}$$
(3)

Where w_{ji} is the weight of the link connecting neuron j to i, n is the learning step, η is the learning rate, α is the momentum constant, and δ_{pj} is the error term.

3. After presenting all of the patterns, if \hat{Y} is a vector of n predictions, and Y is the vector of the observed values corresponding to the inputs to the function which generated the predictions, then the MSE of the predictor can be estimated by:

$$MSE = \frac{1}{n} \sum_{i=1}^{n} (\hat{Y}_i - Y_i)^2$$
 (4)

4. If $(MSE < MSE_{target})$ or $(epochs > epochs_{max})$, then stop, otherwise, go to step 2.

The variation of the MSE during the training is shown in Fig. 6. The MSE target is achieved in 140 epochs and the training is terminated. As Fig. 6 illustrates, the best training performance is 0.0030136 at epoch 113 and that is acceptable and promising.

For calculating the sensitivity of each parameter in the ANN, the specified parameter has maximum and minimum quantity and other parameters have average quantity. In this condition, the sensitivity is a difference of output in the normalized situation. Fig. 7 shows the sensitivity analyzed by using the ANN. As Fig. 7 shows, R_P and μ have the most and the least influence on the output, respectively.

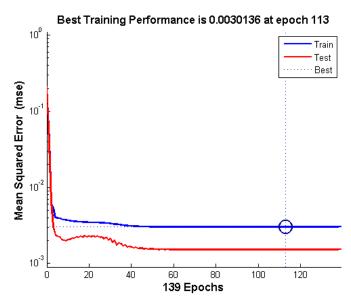


Fig. 6 Variation of MSE during ANN training

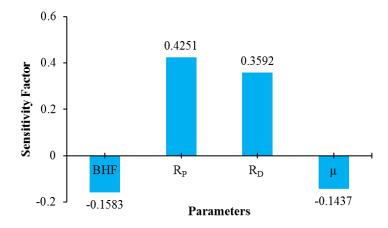


Fig. 7 ANN sensitivity analysis

Finally, Table 6 is presented with the aim of comparing the ANN results with the FEM results regarding 25 input data.

Table 6 Comparison between RSM and ANN results

Trial no.	WH		Error	Trial no.	WH		Error
-	FEM	ANN			FEM	ANN	
1	1.71	1.71	0.00	14	1.79	1.74	0.05
2	2.01	2.05	-0.04	15	1.76	1.77	-0.01
3	2.05	2.01	0.04	16	1.64	1.65	-0.01
4	1.39	1.40	-0.01	17	1.75	1.78	-0.03
5	1.62	1.62	0.00	18	1.76	1.71	0.05
6	1.67	1.68	-0.01	19	1.86	1.92	-0.06
7	1.69	1.66	0.03	20	1.56	1.63	-0.07
8	1.84	1.88	-0.04	21	1.43	1.41	0.02
9	1.44	1.43	0.01	22	1.85	1.82	0.03
10	1.95	1.98	-0.03	23	1.49	1.49	0.00
11	1.48	1.49	-0.01	24	1.69	1.69	0.00
12	2.15	2.02	0.13	25	1.72	1.77	-0.05
13	1.43	1.45	-0.02				

3. Comparing RSM and ANN models

The comparison of both methods demonstrates that ANN is much accurate in making prediction than RSM. The last step of an RSM and an ANN design is the verification of the prediction models on the basis of error function. The multivariable functional approximation by RSM and ANN is evaluated by using a continuous error metric such as the mean squared error (MSE) and the root mean squared error (RMSE). In Table 7 a comparison between two models according to the evaluation method is shown. It is observed that the coefficient of determination, denoted R^2 , of 0.948 and 0.976 for RSM and ANN, respectively, is obtained This amount represents the superiority of ANN over RSM.

Table 7 Comparison between two models according to evaluation method

Model	Evaluation method								
	Average error %	MSE	RMSE	\mathbb{R}^2	R ² (adj)				
RSM	2.167	0.002	0.047	0.948	0.875				
ANN	1.669	0.001	0.032	0.976	0.939				

The design matrix along with the FEM, RSM and ANN results for the testing data is shown in Table 8. It can be seen that the output values predicted by the ANN are closer to the FEM results.

Table 8 Design matrix along with FEM, RSM and ANN results for testing data

Trial no.	Leve	Levels of input factors (coded)					
	R_D	R_P	μ	BHF	FEM	RSM	ANN
1	0	-2	0	-2	1.39	1.38	1.40
2	-2	0	-2	0	1.59	1.56	1.61
3	0	0	-2	-2	1.84	1.76	1.79
4	-2	-2	0	0	1.19	1.16	1.20
5	2	-2	2	-2	1.72	1.70	1.70

Fig. 8 and Fig. 9 illustrate a comparison of the *WH* error profiles for training and testing data. The maximum absolute percentage error in the ANN prediction is found to be around 5.84% while in the case of the RSM model, it is around 7.60%. Thus, it can be concluded that the ANN model predicts more accurately than the RSM model.

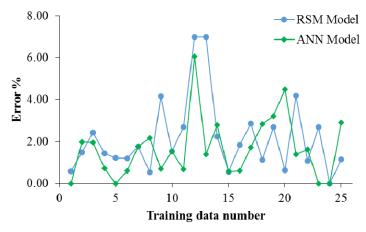


Fig. 8 Comparison of error profiles for WH

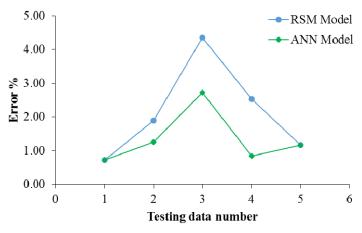


Fig. 9 Comparison of RSM and ANN predictions of WH for testing data

4. Conclusions

This study demonstrates a comparative analysis of the modelling approaches by using RSM and ANN for the *WH* prediction in deep drawing of aluminium AA5754. The CCD for four parameters including 25 samples is employed to generate the input—output database required for the development of RSM and ANN models.

It has been observed that by decreasing R_D and R_P and increasing μ and BHF, WH is reduced, therefore, the optimum value of these parameters is recommended for preventing wrinkling in the deep drawing process.

The performance of the two models is compared based on prediction accuracy. Consequently, the following conclusions are drawn from the present investigation:

- The performance of the ANN model is found to be better compared to the RSM model in terms of the WH prediction both for the training and the testing data.
- The expense of using the ANN approach is greater than when the RSM approach is used due to time consumption.
- Both approaches show that R_P has the strongest effect and μ has the minimal effect on WH.
- The result of the designed ANN and RSM is in agreement with the training and testing data.

Among different trained multilayer perceptron architectures, the 4-20-1 network developed by using the Bayesian Regularization Algorithm is the optimum network model for the *WH* prediction in deep drawing of aluminum AA5754.

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