1. Introduction

Compaction of forest soils is a major problem in ground-based timber harvesting with heavy machinery that can change the physical and chemical properties of the soil, soil fauna, and plant diversity (Farrakh Nawaz et al. 2013) and result in extensive damage that can persist for many years (McColl 1995). Compaction involves the rearrangement and closer packing of the solid soil particles, which results in adverse soil changes such as increased bulk density (Hatchell et al. 1970, Froehlich et al. 1981), reduced total porosity (Rab 1994, Najafi et al. 2009, Ezzati et al. 2011, Solgi et al. 2013), reduced soil permeability, infiltration capacity, and water movement (Froehlich et al. 1981, Murray and Buttle 2004, Ezzati et al. 2012), and increased surface runoff and erosion (Greacen and Sands 1980, Safari et al. 2016). Compaction that reduces air-filled macroporosity to below 10% of the total soil volume can restrict air diffusion and severely limit microbial activity, root proliferation, and plant growth (Greacen and Sands 1980, Brady and Weil 2002, Ampoorter et al. 2007). Ultimately, soil compaction can reduce tree height, diameter, and volume growth (Williamson and Neilsen 2003, Murphy et al. 2004, Tan et al. 2006).

The damage caused by harvesting equipment is related to three major compacting forces exerted on soils:

⇒ a vertical force due to dynamic load of wheels
⇒ shear stress caused by slippage of wheels

Although the effect of these forces strongly depends on the number of equipment passes, various other factors further modify the extent and severity of soil compaction, including inherent soil properties such as soil texture, soil structure, soil organic matter,

In mountainous forests with their inherently uneven topography, however, it is often difficult to maintain the recommended grades (Dykstra and Heinrich 1996, Najafi et al. 2009). Here, skid trails may traverse steep portions of slopes only by installing frequent switchback curves (Cavalli and Grigolato 2010). However, whereas vehicle-soil interactions are tolerably well understood on straight skid trails (e.g., Jamshidi et al. 2008, Najafi et al. 2009, Solgi et al. 2013, Solgi and Najafi 2014, Solgi et al. 2016), our understanding of the effects of ground-based harvesting traffic on soil physical properties in skid trail switchbacks is still very limited. Despite the prevalence on mountainous terrain of skid trail curves, where vertical forces, sheer stress, and engine vibration are likely to be greatest, the effects of skidding in switchbacks is virtually undocumented (but see Thawornwong 1996). For example, in a recent detailed review of machinery-induced effects on forests soils, there was no coverage of switchbacks at all (Cambi et al. 2015).

The aim of this study was thus to investigate whether skidding would result in more adverse soil physical properties (dry bulk density, total porosity, macroporosity, and microporosity) in switchbacks compared to straight skid trail segments. Specifically, we hypothesized that physical soil properties following skidding would:

⇒ differ between switchbacks and straight segments of the skid trail
⇒ depend on the degree of curvature of the switchback
⇒ vary with position within the switchback
⇒ depend on the slope gradient.

2. Material and methods

2.1 Site Description

The study was conducted during August-September 2014 in compartment 41 of the third district in Shenrood forest, Guilan Province, northern Iran (36°31′56″ N to 36°32′11″ N latitude and 51°47′49″ E to 51°47′56″ E longitude). The forest is dominated by oriental beech (Fagus orientalis Lipsky) with an average canopy cover of 80%, stand density of 170 trees ha⁻¹, mean tree diameter of 29.7 cm, and mean tree height of 22.9 m. The soil class is a Cambisol (World Reference Base (WRB), FAO 2015) and soil texture is a clay-loam. The study area is located at an elevation of approximately 800 m above sea level with a northerly aspect. The average annual rainfall recorded at the closest national weather station about 20 km from the research site is 860 mm. The maximum mean monthly rainfall of 120 mm usually occurs in October, while the minimum rainfall of 25 mm occurs in August. The mean annual temperature is 15°C, with lowest temperatures in February. The average depth of soil to the bedrock is 70 cm. At the time of skidding, the weather was dry and warm; the average water content of the soil was 210 g kg⁻¹ (21%). The soil had not been driven on before the experiment.

At the study site, a combination of group selection and single-tree selection silvicultural treatments was applied. In Hyrcanian forests, harvesting and silviculture operations are most common in autumn and winter, while extraction of logs is usually completed in spring and summer. Harvesting and processing are typically performed by hand-felling using chainsaws. Highly mechanized systems, such as harvesters and feller-bunchers, are not used because most of the mature hardwood forests are located on mountainous sites with steep slopes or in lowlands on clay soils sensitive to machine disturbance. Instead, transportation of logs from forest stand to roadside is generally done with cable skidders such as the rubber-tired »Timberjack 450C« skidder (no chains or tracks were installed on the skidder during skidding) with tire size of 775×813 mm, a weight of 10,257 kg, engine power of 132 kW, and a specific ground pressure of 221 kPa.

2.2 Experimental Design and Data Collection

For this study, a skid trail containing multiple switchbacks, of varying curvature, that encompassed a range of longitudinal slope steepness but no lateral slope was delineated. A 2×2 factorial experimental design (2 slope classes × 2 curvature classes) with three replicates each of the four treatment combinations was used, resulting in a total of 12 experimental units (switchbacks). Based on the longitudinal profile of the skid trail, trail segments that ranged between 4–12% in slope were classified as gentle (≤20%) and those between 24–28% as steep (>20%) (cf. Najafi et al. 2010). For each slope class, two curvature classes were established: curves with a high deflection angle of 60–70° (narrow) and curves with a low deflection angle of 110–130° (wide). The deflection angle of a curve was measured from a single measuring location positioned...
at the point beyond the curve where the two extrapolated straight skid trail segments would have intersected (Fig. 1). The deflection angle was determined by measuring the azimuths of the two lines with a compass and computing the differences between the two azimuths.

At each experimental unit, 9 plots (2 m long × 4 m wide) were established at different positions in or near the switchback and soil samples were collected both prior to skidding and after three passes with an unloaded skidder (Fig. 2). Four switchback positions were sampled: one plot was established in the middle (apex) of each curve (central plot, CP), one each 3 m away on either side of the CP (first plots, FP), one each 3 m further out from the FP (second plots, SP), and one each 15 m further out from the SP (third plots, TP). In addition, two plots were placed on straight segments of the skid trail on either side of the switchback, 30–50 m away from the SP.

Within each 2 m long plot, soil samples were collected in three locations along each of two randomly placed (but ≥1 m apart) 4 m wide transects that ran across the wheel track perpendicular to the direction of travel. The three soil samples on each transect were taken at 0–10 cm soil depth from the middle of the left wheel track, between the wheel tracks, and the middle of the right wheel track. Finally, a total of 28 soil samples were taken from undisturbed (control) locations, randomly dispersed throughout the study area but at least 50–60 m (ca. two tree lengths) perpendicular distance from the skid trail where no visual impact of skidding was observed.

Soil samples were collected with a soil hammer and rings (diameter 5 cm, length 10 cm) and immediately put in polyethylene bags and labeled. Samples were brought to the laboratory and promptly weighed before the water content was quantified gravimetrically by oven drying the samples at 105°C for 24 h (Kalra and Maynard 1991).

Dry soil bulk density ($D_b$, g cm$^{-3}$) was calculated as Eq. (1):

$$D_b = \frac{W_d}{VC}$$  (1)

Where:
$W_d$ is the weight of dry soil, g
$VC$ is the volume of soil cores, 196.25 cm$^3$. 

---

Fig. 1 Sketch of the skid trail layout showing the measuring location from which the deflection angle ($\alpha$) was measured. Narrower curves have a deflection angle $\alpha=60–70°$ whereas wider curves have a deflection angle $\alpha=110–130°$. 

Fig. 2 Sketch of the sampling layout at each experimental unit (switchback) on the skid trail. Shown are the plots located at different positions in the switchback: central plot (CP) at the apex of the curve; first plots (FP) each 3 m on either side of the CP; second plots (SP) each 3 m further out from the FP; third plots (TP) each 15 m further out from the SP. The full design included 2 additional plots on straight segments of the trail (SST) located on additional 30–50 m beyond the TP (not shown). Within each plot, three soil samples each were taken from a depth of 0–10 cm along two parallel transects, including within the left and right wheel tracks and between the tracks.
Effects of Ground-Based Skidding on Soil Physical Properties in Skid Trail Switchbacks

Total soil porosity \((TP, m^3 m^{-3})\) was calculated as Eq. (2):

\[
TP = (1 - \frac{D_b}{2.65})
\]

Where:

\(2.65, g \text{ cm}^{-3}\) is the soil particle density (Freeze and Cherry 1979)

Microporosity \((MP, m^3 m^{-3})\) was calculated as Eq. (3):

\[
MIP = \theta_m \times D_b
\]

Where:

\(\theta_m\) water content on a mass basis, % (Solgi et al. 2016).

Macroporosity \((MP, m^3 m^{-3})\) was calculated as Eq. (4):

\[
MP = TP - MIP
\]

2.3 Statistical Analysis

Samples were averaged to the plot-level for analysis (i.e. across transect locations). Two-way ANOVA was used to assess the significance of differences in \(D_b\), \(TP\), \(MP\), and \(MIP\) between different slope classes, curvature classes, and their interaction. Tukey’s HSD test was used to determine which combinations of slope and curvature differed statistically significantly from each other and from straight skid trail segments and controls, at an overall \(\alpha\)-level of 0.05. For each slope class \(\times\) curvature class combination, Tukey’s HSD was also used to determine whether \(D_b\), \(TP\), \(MP\), and \(MIP\) differed by position within the switchback. The SPSS software version 11.5 was used for all statistical analyses.

3. Results

Average values of all four soil physical properties differed significantly between switchbacks and straight segments of the skid trail and depended strongly on the degree of curvature (Table 1). Averages of \(D_b\), \(TP\), \(MP\), but not \(MIP\), also depended on the slope gradient of the skid trail and, in the case of \(D_b\) and \(MP\), on the interaction of slope class \(\times\) curvature class (Table 1). On average, \(D_b\) (1.21 g cm\(^{-3}\)) was greatest, while \(TP\) (0.55 m\(^3\) m\(^{-3}\)) and \(MP\) (0.21 m\(^3\) m\(^{-3}\)) were least, in narrow curves on steep terrain, whereas \(D_b\) (0.94 g cm\(^{-3}\)) was least, and \(TP\) (0.64 m\(^3\) m\(^{-3}\)) and \(MP\) (0.34 m\(^3\) m\(^{-3}\)) greatest, in wide curves on gentle terrain.

Skidding increased average \(D_b\) by 14–57% on straight skid trail segments, 14–86% in wide curves, and 29–100% in narrow curves compared to undisturbed controls (Table 2). Skidding decreased average \(TP\) by 8–25% on straight trail segments, 9–32% in wide curves, and 12–36% in narrow curves compared to undisturbed controls. Similarly, skidding decreased average \(MP\) by 23–50% on straight trail segments, 23–71% in wide curves, and 27–81% in narrow curves compared to undisturbed controls. In contrast, skidding increased average \(MIP\) by 21–38% on straight trail segments, 17–54% in wide curves, and 21–58% in narrow curves compared to undisturbed controls.

Regardless of curvature class, the effects of skidding on soil physical properties differed strongly and significantly by position within the switchback, with the greatest effects at the apex of the curve (Table 2). A maximum in \(D_b\) and \(MIP\), and a minimum in \(TP\) and \(MP\), was observed in the \(CP\), with decreasing effects of skidding the further the plots were positioned from the apex of the curve. In most cases, a significant difference in responses was already seen between the \(CP\) and \(FP\), and in all cases between the \(CP\) and \(SP\) and \(TP\). However, even the \(SP\) and \(TP\) were significantly different for all four soil properties in narrow curves on gentle slopes. In general, differences in average soil physical properties among positions along the switchback were more pronounced on gentle than steep slopes.

Table 1

<table>
<thead>
<tr>
<th>Source variable</th>
<th>Dry bulk density</th>
<th>Total porosity</th>
<th>Macroporosity</th>
<th>Microporosity</th>
</tr>
</thead>
<tbody>
<tr>
<td>Slope class</td>
<td>(\leq 0.01)</td>
<td>(\leq 0.01)</td>
<td>(\leq 0.01)</td>
<td>0.115</td>
</tr>
<tr>
<td>Curvature class</td>
<td>(\leq 0.01)</td>
<td>(\leq 0.01)</td>
<td>(\leq 0.01)</td>
<td>(\leq 0.01)</td>
</tr>
<tr>
<td>Slope (\times)</td>
<td>(\leq 0.01)</td>
<td>(0.815)</td>
<td>(\leq 0.01)</td>
<td>0.613</td>
</tr>
</tbody>
</table>

*p values less than 0.05 are given in bold
MP greater, on straight skid trail segments than in skid trail curves, but these effects were not statistically significant for the third plots in narrow curves on slopes ≤20% or for second and third plots in all other cases.

4. Discussion

In this study, we are among the first to document the adverse effects of frequent switchback curves that characterize skid trails traversing steep slopes in mountainous forests with uneven topography (Cavalli and Grigolato 2010). Whereas adverse effects on soil physical properties by ground-based timber harvesting with heavy machinery has been amply documented on skid trails (e.g., Grigal 2000, Ampoorter et al. 2007), this study extends these findings showing that:

- such adverse effects are enhanced in skid trail switchbacks compared to straight segments
- narrower, more space-conserving switchbacks result in greater increases in soil bulk density than wider, less space-conserving switchbacks
- these effects are most pronounced toward the apex of the switchback curve
- the effect of harvest traffic is greatest on gentle slopes.

Table 2 Average soil properties of a Cambisol in an undisturbed control area (UN) and following three passes of a Timberjack 450C skidder on a skid trail on two slope gradients (≤20% and >20% longitudinal profile of the skid trail) and two curvature classes (high deflection angle of 60–70° = narrow curves and low deflection angle of 110–130° = wide curves) at various positions: the central plot (CP) at the apex of the curve; first plots (FP) each 3 m on either side of the CP; second plots (SP) each 3 m further out from the FP; third plots (TP) each 15 m further out from the SP; and straight segments of the skid trail (SST) 30–50 m further out from the TP.

<table>
<thead>
<tr>
<th>Slope Class</th>
<th>Curvature Class</th>
<th>Position</th>
<th>Soil bulk density ($D_b$, g cm$^{-3}$)</th>
<th>Total porosity ($TP$, m$^3$ m$^{-3}$)</th>
<th>Macroporosity ($MP$, m$^3$ m$^{-3}$)</th>
<th>Microporosity ($MIP$, m$^3$ m$^{-3}$)</th>
</tr>
</thead>
<tbody>
<tr>
<td>≤20%</td>
<td>Narrow</td>
<td>TP</td>
<td>0.9$^f$</td>
<td>0.66$^d$</td>
<td>0.37$^{a}$</td>
<td>0.29$^{a}$</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SP</td>
<td>1.0$^f$</td>
<td>0.61$^c$</td>
<td>0.28$^{b}$</td>
<td>0.33$^{b}$</td>
</tr>
<tr>
<td></td>
<td></td>
<td>FP</td>
<td>1.2$^i$</td>
<td>0.55$^b$</td>
<td>0.23$^{b}$</td>
<td>0.32$^{b}$</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CP</td>
<td>1.4$^i$</td>
<td>0.49$^a$</td>
<td>0.10$^a$</td>
<td>0.39$^a$</td>
</tr>
<tr>
<td>≤20%</td>
<td>Wide</td>
<td>FP</td>
<td>1.0$^i$</td>
<td>0.61$^b$</td>
<td>0.24$^b$</td>
<td>0.32$^b$</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CP</td>
<td>1.1$^i$</td>
<td>0.57$^a$</td>
<td>0.10$^a$</td>
<td>0.32$^a$</td>
</tr>
<tr>
<td>&gt;20%</td>
<td>Narrow</td>
<td>FP</td>
<td>1.1$^i$</td>
<td>0.57$^a$</td>
<td>0.19$^a$</td>
<td>0.32$^a$</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CP</td>
<td>1.2$^i$</td>
<td>0.54$^a$</td>
<td>0.15$^a$</td>
<td>0.35$^a$</td>
</tr>
<tr>
<td>&gt;20%</td>
<td>Wide</td>
<td>FP</td>
<td>1.1$^i$</td>
<td>0.54$^a$</td>
<td>0.19$^a$</td>
<td>0.35$^a$</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CP</td>
<td>1.2$^i$</td>
<td>0.52$^a$</td>
<td>0.15$^a$</td>
<td>0.35$^a$</td>
</tr>
</tbody>
</table>

Different superscript letters across a row indicate a statistical difference among positions at alpha = 0.05.
As expected, increased soil bulk density (compaction) translated into reduced macroporosity and total porosity and increased microporosity, which is a commonly observed response in the pore size distribution following skidding (Greacen and Sands 1980).

In this initial investigation of the effects of harvest traffic in switchbacks, we did not formally examine the specific causes that may be responsible for more adverse soil physical conditions along the curve. Nonetheless, as increased soil bulk density from harvest traffic is primarily a function of universal physical forces (Pacejka 2012), the most plausible causes may be hypothesized for future exploration. Greater effects of skidding in switchbacks than on straight segments of the skid trail, greater effects in narrow than wider curves, and non-constant effects on soil physical properties across different positions within the switchback are largely due to:

\[ \Rightarrow \text{lateral weight/load transfer} \]
\[ \Rightarrow \text{lower speed in curves}. \]

Lateral weight/load transfer is the change in the distribution of the skidder weight and its load on the skidder axles and wheels that occurs when a vehicle enters a curve, which results in higher ground pressure of the wheels on the outside of the curve (and lower ground pressure of the wheels on the inside of the curve), and thus uneven soil disturbance of the wheel tracks within the skid trail (Pacejka 2012). As physical forces are particularly pronounced in narrow curves (Pacejka 2012), soils in skid trails with narrow curves are more susceptible to greater compaction than in wide curves. In addition to weight/load transfer that occurs in curves, skidders slow to enter and pass through a curve, thus spending more time in curves than on straight segments of the skid trail (Thawornwong 1996). As skidders slow to enter and pass through a curve, engine vibration increases, thus compacting the top soil more in curves than on skidder trail segments that are traversed at higher speeds (Horn et al. 1989, Solgi and Najafi 2014). The combination of greater weight/load transfer and lower machine speeds with greater vibration results in soil compaction that is particularly pronounced in narrower curves and on steeper slopes, where lower speeds are required to navigate narrower curves. Differential weight/load transfer and speed may also explain the non-constant effects on soil physical properties across different positions within the switchback, regardless of deflection angle and slope gradient. In contrast to paved highway roads that are engineered to have a more or less constant radius throughout the curve for a constant centrifugal force that enhances the safety even at higher speeds (Slimi et al. 2013), skid trails typically do not have a constant radius throughout the curve (as is often the case, including in the current study) such that the narrowest portion of the switchback typically occurs at the apex of the curve. Thus, weight/load transfer in the apex of the curve is greatest, speeds are lowest, with the result that soil compaction at this position in the curve is greatest. Finally, although soil bulk density was greater and macroporosity was smaller on steep slopes than on gentle slopes on straight segments of the skid trail, as is typically the case (e.g., Solgi and Najafi 2014), and in most switchback positions in wide curves, this was not the case at the apex of narrow curves. Greater soil loss in narrower curves on gentler slopes (Thawornwong 1996) could compensate for the soil damage incurred by increased steepness, explaining the lack of a slope effect at the apex of narrow curves, and may again reflect differential skidder speeds: due to the lower traction of machinery on steeper slopes, skidder speeds on steep slopes may already be reduced compared to more gentle slopes (Najafi et al. 2009), resulting in a larger relative reduction in speed as machinery enters a switchback on gentle slopes.

Regardless of the specific causes of soil damage in switchbacks, our results indicate that, after as few as three equipment passes, the apex of the switchback curve may be particularly vulnerable to deteriorating soil conditions following skidding, especially given that soil conditions on both slope gradients came close to the critical threshold values shown to be detrimental to future plant growth and long-term site productivity. In the central plots, particularly in narrow curves, bulk densities fell only slightly short of the critical threshold between 1.40–1.55 g m\(^{-3}\), above which plant roots cannot penetrate soils with light and medium texture (Kozlowski 1999). Similarly, air filled macroporosity below 10% of the total soil volume in the apex of narrow curves in both slope gradients may severely limit air diffusion, microbial activity, and root proliferation in most soils and cause site productivity to decline (Brady and Weil 2002, Ampoorter et al. 2007). Thus, on a portion of the site, a loss of future site productivity has already been achieved after only three skidder passes, which must be regarded as a low traffic volume considering that skid trails are designed to concentrate as much equipment traffic on as small an area as possible (e.g., Hatchell et al. 1970, Zenner et al. 2007). Although we did not investigate the effects of greater traffic frequencies in this study, given that the majority of adverse effects on soil physical properties typically occurs in the first three passes of a vehicle, with modest additional impact with subsequent passes (Hatchell et al. 1970, Zenner et al. 2007, Jamshidi et al. 2008), it could be expected that the observed pattern
of effects in straight and curved segments of the skid trail would hold with greater traffic. However, further studies will be needed to assess whether the observed effects of curvature and switchback position remain constant or diminish as increasing traffic volume increases soil damage toward critical threshold values on ever larger proportions on the trail (cf. Kozlowski 1999). Either way, differential soil damage at various positions along skid trails containing switchbacks indicates that soil damage assessed on straight segments of skid trails may severely underestimate the actual soil damage in mountainous areas that include curves. Differences between straight segments and the apex of the curve of 29% for total porosity, 56% for dry bulk density, and 74% for macroporosity indicate that these differences can be sizeable, at least for some portions of the harvest area.

The results of this study reiterate recommendations for careful planning of skid trail networks that includes confining skidder traffic to as few designated skid trails as possible, maintaining slope gradients of skid trails that are as low as possible, and keeping skid trails as straight as possible. This can minimize the proportion of total stand area adversely impacted by traffic, reduce damage to the residual stand and disturbances to the forest floor, and decrease skidder travel time (e.g., Dey 1994, Grigal 2000, Zenner et al. 2007). In mountainous forests with uneven topography, where it is difficult to maintain recommended grades for skid trails of 10-20% (Dykstra and Heinrich 1996, Najafi et al. 2009) or ≤30% for rubber-tired skidders on short pitches in adverse terrain (Dey 1994), installing frequent switchback curves is often unavoidable (Cavalli and Grigolato 2010). Given greater soil bulk density and reduced porosity in narrower compared to wider curves following skidder traffic, particular attention must be paid to the placement of these curves for a more optimal routing of machinery.

5. Conclusions

In the current study, we compared the effect of skidding on dry bulk density, total porosity, macroporosity, and microporosity in the straight segments of the skid trail and in various positions within switchbacks of differing trail curvature (deflection angle) on different slope gradients. We have concluded that adverse skidding effects on switchbacks are substantially greater than on straight segments of the skid trail. Despite the limitations of this initial study, which investigated soil physical properties on only one soil type (Cambisol) after a fixed number of passes with one particular harvesting machine, the universality of physical forces that induce soil damage on skid trails (Pacejka 2012) suggests that some of the observed results may be broadly generalizable to other soils, forest types, climates, years, and equipment. If switchback curves are necessary to provide access to the entire cutting area, these generalizations include that:

- soil physical properties such as bulk density and porosity can be expected to be more strongly adversely affected in the curves of the skid trail than on straight segments
- soil damage can be expected to depend on the deflection angle of the switchback, with greater severity in narrower than in wider curves
- the adverse effects on soil physical properties can be expected to be worse in the apex of the curve, regardless of slope gradient or curvature
- the effects on soil physical properties of a steeper slope gradient can be expected to be more adverse in the straight segments of a skid trail and all switchback positions in wider, but not necessarily narrower, curves.

In conclusion, our results indicate that simple extrapolation of soil-machine interactions from straight segments of skid trails to the entire skid trail may not be prudent in mountainous areas, where trails include numerous switchback curves. This may particularly be the case given that only three passes of harvesting equipment (i.e., low traffic volume) were capable of inducing levels of soil damage that approached critical threshold values detrimental to plant growth and long-term site productivity in switchback curves. The subsequent implication for the layout of skid trail systems in mountainous terrains is that optimal routing of the extracting ground-based machinery may require that particular attention be paid to the placement of skid trail curves. In addition to skid trail planning, primary timber extraction planning needs to consider the type of skid trail (i.e., whether the trail is temporary or permanent), the intensity and period of logging extraction, and the size of the extracted wood to minimize adverse effects on the stand. Further research is required, however, to verify the specific causes of adverse effects of skidding in switchbacks on physical soil properties, to confirm these effects across a broader range of soil conditions, and determine how these effects are modified by increased traffic intensity.

6. References


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