# Thermal Performance of Heat Pipe Array in Battery Thermal Management

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Abstract: In the present study, the thermal performance of a power battery cooling system using copper tubes and heat pipes was compared. The effects of coolant flow rate, coolant inlet temperature, and input power were discussed by numerical methods. The numerical computation results showed that heat pipe could more significantly enhance the heat transfer performance of the battery cooling system than the copper rod. Within the scope of this study, the heat pipe reduced the maximum temperature by 41,6% - 60,9%. The distributions of the temperature ratio of the battery surface, together with the heat flux and streamlines around the heat pipe condenser were also illustrated.

Keywords: battery thermal management; heat pipe; heat transfer enhancement; temperature difference

### **1 INTRODUCTION**

Lithium-ion battery is the promising energy storage equipment for electric vehicles and hybrid electric vehicles for its high energy density [1, 2]. The optimum working temperature of the lithium battery is 25 °C - 40 °C [3-6], the maximum temperature difference should not exceed 5 °C in one battery pack [7, 8]; otherwise, it may cause serious safety problems [6, 7]. The heat pipe cooling system which uses liquid-gas phase change without consuming extra power has become the most promising cooling method in lithium-ion battery thermal management system with excellent heat transfer performance and rapid response capability [3, 4, 9, 10].

The power battery generates heat more than 50 W [11, 12], and more during acceleration and other high charging or discharging conditions. Rao et al. [4] conducted experimental research which shows that the maximum temperature of the battery surface can be controlled below 50 °C when heat generation of the battery is less than 50 W. However, the maximum temperature difference is about 8 °C. The heat load should not exceed 30 W to maintain the surface temperature difference within 5 °C. The experiment studied by Wang et al. [13] pointed out that the battery temperature can stay below 70 °C when the heat generation per cell is between 20 - 40 W. Or the amount of heat generation cannot exceed 10 W in order to achieve the maximum temperature below 40 °C. Ye et al. [11] found that the heat transfer coefficient of the heat pipe condenser surface decreased significantly along the flow passage, causing unevenness of the battery temperature. Dummy heat pipes and copper fins could enhance the heat transfer and temperature uniformity. Ye et al. [14] also pointed out that the addition of fins at the heat pipe condenser sections has a significant effect on lowering the maximum temperature and the temperature difference on battery surface.

More information is needed to study the influence parameters of the heat pipe cooling system on a lithium battery. In this paper numerical investigations were conducted on heat transfer characteristics and flow details in a heat pipe cooling system for the high-power lithium battery. The validity of the numerical models and grids used in this study was carefully checked and calibrated by comparing with experimental data in the literature. Amounts of indicators such as temperature, heat flux, and pressure loss were extracted to characterize the heat performance of heat pipe cooling system.

#### 2 NUMERICAL SETUP

#### 2.1 Geometry Models and Simplifications

Fig. 1 shows a configuration of the heat pipe cooling system for a prismatic battery pack. Between two prismatic batteries ( $118 \times 63 \times 13$  mm) were sandwiched evaporator sections of four heat pipes. The heat generated in the battery is transferred to the condenser section through the heat pipe and then emitted into the coolant flow through the cooling passage ( $300 \times 60 \times 12$  mm). Each heat pipe was flattened from tubular condenser ( $\emptyset = 6,0$  mm) to rectangular evaporator section  $(2,0 \times 8,5 \text{ mm})$ . The copper cooling system is designed as similar as the heat pipe cooling system except that the heat pipes are turned to pure copper rods. Cross section radius of vapor core is 0,002 m. The total length of the heat pipe is 0,198 m. The porosity of the wick region is 0,50. The copper cooling system is designed similar to the heat pipe cooling system except that the heat pipes are turned to pure copper rods.



Figure 1 The configuration of the heat pipe cooling system for a prismatic battery pack

It is complex and time-consuming to model all details for a battery pack cooled by heat pipe for phase changes and other phenomena in heat pipe. Even in the case of simulating one heat pipe, high computational resources are necessitated to characterize the mass and heat transfer during transient charging or discharging of the cell. Thus, one more efficient approach for numerical computation is adopted. The thermal behavior of a heat pipe on battery cooling would be treated as a thermal network of various components, and then the transient behavior can be described by first order linear ordinary differential equations [15]. Additionally, solving electro-chemical reactions of a battery is also too complicated for only presenting the thermal behavior of battery cell (multi-layer structure). Therefore, a simplified model without considering electro-chemical reactions is applied to present the heat generation of the battery, as well as the thermal properties of a multi-layered battery cell. This approach is well validated by comparisons with experimental and numerical studies and is applied in many pieces of literature [1, 9, 11, 15].

# 2.2 Model Formulation of the Heat Pipe 2.3.1 Copper Shell

The thermal properties of copper were applied directly to the copper shell during this simulation because the heat transfer through the copper shell of the heat pipe is entirely conduction.

#### 2.3.2 Wick Region

In the present study, a heat pipe with a higher maximum heat transfer limit than the target heat load has been selected to avoid drying during operation. The wick region was considered as a porous structure filled with water. A widely accepted model developed by Chi et al. [16] can be used to calculate the effective thermal conductivity of the wick region  $k_{\text{wick}}$ :

$$k_{\text{wick}} = \frac{k_{\text{l}}[(k_{\text{l}} + k_{\text{s}}) - (1 - \varepsilon)(k_{\text{l}} - k_{\text{s}})]}{[(k_{\text{l}} + k_{\text{s}}) + (1 - \varepsilon)(k_{\text{l}} - k_{\text{s}})]}$$
(1)

where  $k_1$  and  $k_s$  are respectively the thermal conductivity of working fluid and sintered copper powder porous wick, and  $\varepsilon$  is the porosity. In this study, the effective thermal conductivity of the wick region was calculated to be 1,814 Wm<sup>-1</sup>K<sup>-1</sup>.

The volumetric averaged density of the mixture of water and sintered copper powder porous wick could be utilized to determine the density of the wick region by Eq. (2), and the specific heat capacity is obtained according to Eq. (3).

$$\rho_{\rm wick} = \varepsilon \rho_{\rm l} + (1 - \varepsilon) \rho_{\rm s} \tag{2}$$

$$C_{\text{wick}} = [\varepsilon \rho_{\rm l} C_{\rm l} + (1 - \varepsilon) \rho_{\rm s} C_{\rm s}] / \rho_{\rm wick}$$
(3)

where  $r_{\text{wick}}$ ,  $r_{\text{l}}$ ,  $r_{\text{s}}$  are respectively the densities of the wick, working fluid and copper powder,  $C_{\text{wick}}$ ,  $C_{\text{l}}$ ,  $C_{\text{s}}$  are respectively the specific heat capacity of the wick, working fluid and copper powder, and  $\varepsilon$  is the porosity.

#### 2.3.3 Vapor Core

The vapor flow was considered incompressible, laminar and fully developed. By assuming the relationship between pressure drop and temperature drop in accordance with the Clapeyron equation and the ideal gas law [17, 18], the effective thermal conductivity of the vapor core in a tubular heat pipe can be calculated by Eq. (4) [17].

$$k_{\rm vapor} = \frac{r_{\rm v}^2 L^2 \rho P_{\rm v}}{8\mu R T^2} \tag{4}$$

where  $r_v$  is the cross-section radius of the vapor core. *L* is the latent heat of working fluid.  $\rho$ ,  $P_v$ ,  $\mu$ , *R* and *T* is respectively the density, the saturation pressure, the dynamic viscosity, the gas constant per unit mass and the temperature of the water vapor. The  $k_{vapor}$  was calculated as  $4,69 \times 10^6$  Wm<sup>-1</sup>K<sup>-1</sup> using the properties of saturated water vapor at a temperature of 40 °C.

#### 2.3 Thermal Model of the Battery

Two aluminum blocks of the same size as some commercial power battery were used to simulate batteries [4, 13, 19, 20]. It is assumed that during the entire operation process, the heat generation rate of the battery is a constant value which is regarded as the maximum power during the highest sustainable constant-current discharge rate. In the present research, the heat generation rate is in the range of 20 - 80 W per cell.

#### 2.4 Numerical Procedures

In this calculation, numerical studies were performed by the commercial CFD software-ANSYS Workbench 17.2 FLUENT using a local parallel solver in a doubleprecision mode. Heat radiation transfer is negligible and was not considered.

Block-structured grids with hexahedral elements were employed to realize the spatial discretization of the domain models. Cell orthogonality was ensured by introducing multiple O-grid blocks for heat pipes. Denser girds were applied in the non-slip boundary regions where the flow and temperature gradients are greater, i.e., the area around heat pipes and the endwall of the coolant channel. The grid independence test was performed by gradually refining the mesh size (in this study, three different meshes containing 2628477, 4737970 and 7895174 cells, respectively) to ensure that the mesh size has little impact on the results. The control parameter for grid independence test was the maximum temperature on the battery surface. According to the procedure described [21], the grid convergence index (GCI) was 2,81%. Fig. 2 shows the mesh used in this numerical investigation.



Figure 2 The hexahedral mesh used in the present numerical study

#### 3 MODEL VALIDATION

The results obtained by the computation procedure were well compared with the published experimental data

of Liang [20]. All materials, boundary conditions, and data processing methods are modified according to the experiment of Liang [20]. The computation models include the heat transfer in the solid wall and in the fluid, which is coupled to solve energy equations automatically. The surface of the channel and the insulation section of heat pipes are treated as isolation and no-slip boundaries. The two batteries have a constant volume heat generation rate. At the inlet of the channel, constant velocity was applied. Laminar is used to calculate the viscous due to the inlet Reynolds number. Data are plotted in Fig. 3 for comparison. As illustrated, the maximum deviation between the numerical computation results in this research and the data from the literature [20] were kept within 10%. Thus, the numerical model is considered to be reliable and can be applied to predict the heat performance of the heat pipe cooling system for the battery based on the above validation.



Figure 3 Results of maximum temperature varied with coolant inlet temperature obtained by CFD and experimental data from Liang [20] for comparison

#### 4. RESULTS AND DISCUSSION 4.1 Effects of Coolant Flow Rate

In this section, the effect of coolant flow rate on the battery surface temperature while using heat pipes and copper rods is compared. The input power is set at 40 W/cell while the coolant inlet temperature  $T_c$  is set as 25 °C. The cooling flow rate ranges from 0,5 L/min to 8 L/min. The maximum temperature  $(T_{max})$ , average temperature  $(T_{avg})$ , and temperature difference  $(\Delta T)$  of battery surface with different coolant flow rates for both configurations are shown in Fig. 4.

The trend of  $T_{\text{max}}$  and  $T_{\text{avg}}$  for both heat pipe and copper rod is similar. At first, the  $T_{\text{max}}$  and  $T_{\text{avg}}$  reduced rapidly with the increased coolant flow rate while gradually being gentle when the coolant flow rate reaches 2 L/min, and the temperature difference of the battery surface  $\Delta T$  almost keeps constant.

While the coolant flow rate changes from 0,5 L/min to 8 L/min, the maximum temperature on the battery surface by copper rod changes from 107,81 °C to 84,24 °C, decreased by 21,9%, and that by heat pipe changes from 52,74 °C to 39,77 °C, decreased by 24,6 %. The heat pipe reduced the maximum temperature by 51,1% - 52,8%. While the coolant flow rate changes from 0,5 L/min to 8 L/min, the temperature differences by copper rod change

from 19,34 °C to 18,51 °C, and that by heat pipe changes from 2,08 °C to 1,74 °C. The heat pipe reduced the maximum temperature by 89,3% - 90,6%. Compared to copper rods, heat pipes significantly reduce the maximum temperature and temperature difference on the battery surface.



#### 4.2 Effect of Coolant Inlet Temperature

In this section, the input power is set at 40 W/cell while the coolant flow rate is set at 2 L/min to study the effect of coolant inlet temperature on the heat pipe cooling system. The coolant inlet temperature ranges from 25 °C to 45 °C. The maximum temperature ( $T_{max}$ ), average temperature ( $T_{avg}$ ), and temperature difference ( $\Delta T$ ) of battery surface under different coolant inlet temperatures of copper rod and heat pipe are shown in Fig. 5.



Both  $T_{\text{max}}$  and  $T_{\text{avg}}$  of cooper rod and heat pipe increase linearly as coolant inlet temperature increases. As coolant inlet temperature increases from 15 °C to 35 °C, the maximum temperature  $T_{\text{max}}$  of copper rod increases from 82,85 °C to 102,85 °C, the enhancement is 24,1%; and the data of heat pipe is from 33,91 °C to 53,91 °C, the enhancement is 59,0%. The heat pipe reduced the maximum temperature by 59,1% - 47,6%. The temperature uniformity is less affected by coolant inlet temperature. The temperature difference ( $\Delta T$ ) is always around 19,0 °C and 1,9 °C. The heat pipe reduced the maximum temperature by 89,8%. Compared to copper rods, heat pipes significantly reduce the maximum temperature and temperature difference on the battery surface.

#### 4.3 Effect of Input Power

In this section, the effect of input power on the temperature of the battery surface cooling by cooper rod and heat pipe is studied. The cooling flow rate is set at 2 L/min under  $T_c = 25$  °C, and the input power ranges from 20 W to 80 W. The maximum temperature ( $T_{max}$ ), average temperature ( $T_{avg}$ ), and temperature difference ( $\Delta T$ ) of battery surface with different input powers of the battery are shown in Fig. 6.

As shown in Fig. 6,  $T_{\text{max}}$ , and  $T_{\text{avg}}$  as well as  $\Delta T$  significantly increase as the input power increases. While the input power changes from 20 W to 80 W, the maximum temperature of copper rod increases from 58,84 °C to 160,85 °C, enhancement of 173,4%; and that data of heat pipe increases from 34,38 °C to 62,97 °C, increase of 83,2%. The heat pipe reduced the maximum temperature by 41,6% - 60,9%. The temperature difference of copper rod increases from 9,49 °C to 37,96 °C, and the data of heat pipe increase from 0,96 °C to 3,86 °C. The heat pipe reduced the maximum temperature by 89,8%.



Figure 6  $T_{\text{max}}$ ,  $T_{\text{avg}}$  and  $\Delta T$  of battery with different input power (mass flow rate  $q_v = 2 \text{ L/min}$  under coolant inlet temperature  $T_c = 25 \text{ °C}$ )

## 4.4 Comparison of Local Temperature Distribution between Cooper and Heat Pipe

The distribution of temperature ratio  $(T/T_{avg})$  can represent the temperature difference, and that of battery surface by copper rod and heat pipe is displayed in Fig. 7. In the copper rod cooling structure, the surface temperature gradient of the battery is mainly the longitudinal temperature gradient. In the heat pipe cooling structure, the surface temperature gradient distribution of the battery is very different from that of the copper tube. Temperature gradient occurs between the longitudinal and lateral directions. The temperature gradient along the length of heat pipe is caused by heat conduction from bottom to top, and the temperature gradient along the coolant streamwise is very likely resulted from a reduction in the effective heat transfer coefficient in the flow direction. The increasing coolant flow rate enhances the turbulence intensity, which enhances the mixing of hot water around heat pipe condensers and the cold water on the periphery. It contributes to the increase of the effective heat transfer coefficient in the flow direction and the reduction of the temperature gradient downstream the coolant.



# 4.5 Heat Transfer Distribution in the Heat Pipe Condenser Sections

The thermal performance is significantly affected by the convective heat transfer between the coolant and the cooling structures. Fig. 8 displays streamline and convective heat transfer coefficients at the wall of the copper rod and heat pipe condenser section while the coolant flow rate is  $q_v = 2$  L/min under coolant inlet temperature  $T_c = 25$  °C, and the input power of the battery is 40 W/cell. As can be seen, fewer vortices are produced in the entire flow field for the flow is mainly laminar. It can be seen that the surface heat exchange of the copper rod is very uneven, and the heat exchange is mainly concentrated near the root wall of the battery. On the principle battery side, there is almost no heat exchange. In addition, away from the battery end, there is almost no heat exchange. Compared to copper rods, heat pipe heat transfer is largely unaffected by the height direction, but there is a difference between the circumferential directions.



(a) cooper rod



 Boundary heat flux:
 5000
 10000
 15000
 20000
 25000
 30000
 35000
 40000

 Figure 8 Streamline and Nusselt number on the (a) copper rods and (b) heat pipe condenser sections
 pipe condenser sections

# 5 CONCLUSION

In the present study, the thermal performance of a power battery cooling system using copper tubes and heat pipes was compared. The effects of coolant flow rate, coolant inlet temperature, and input power were discussed by numerical methods. Numerical models and procedures are carefully validated and calibrated with experimental results in the literature. The model and approach demonstrated considerable accuracy and were then employed to sensitivity analysis. Amounts of indicators such as temperature, heat flux, and pressure loss were extracted to describe the characteristics of the heat pipe cooling system. The results can provide some useful guidance for the heat pipe cooling system. Several main conclusions can be drawn as follows:

(1) Compared to copper rods, heat pipes significantly reduce the maximum temperature and temperature difference on the battery surface respectively by 41,6% - 60,0% and 89,8% - 90,6%.

(2) The distributions of the temperature ratio  $T/T_{avg}$ 

display the temperature uniformity of the battery surface, together with the heat flux and streamlines respectively on the copper rod and heat pipe condenser explains the effect of coolant flow rate, coolant inlet temperature and input powers on the performance of the heat pipe cooling system.

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