COST-EFFICIENT ELECTROMAGNETICALLY-ACTUATED ROTATIONAL ADAPTIVE MIRROR DESIGN

Ammar Alzaydi*

Department of Mechanical Engineering, King Fahd University of Petroleum and Minerals, Dhahran 31261, Saudi Arabia.

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Abstract:



This article showcases the innovative use of polymers, reflective polyester, and various flexible films to develop adaptable rotational mirrors. These mirrors employ rotation as a mechanism to amend images tainted by surface inconsistencies. Made with a self-standing Mylar polyester film, the mirror spans 120mm and has a 1mm thickness. Electromagnetic actuation, coupled with a magnetic electrode matrix underneath, allows for the mirror surface's modulation, adjusting the focal point. The inherent mechanical characteristics of the Mylar film mean minimal deflection is necessary for focal changes, heightening the mirror's adaptability and electromagnetic sensitivity. Additionally, the construction process remains uncomplicated and cost-effective. The mirror prototype is designed with two analogous membranes that rotate in harmony around their midpoint, ensuring uniform distribution of the electromagnetic deflection forces. This mirror's functionality was effectively proven by its capability to rectify and refocus images. Distinctly, the mirror boasts rotational dynamics, a partitioned surface to diminish the influence of surface irregularities, and the proficiency to reshape its curvature and focal point in motion. Such innovations are ideal for MEMS devices, aiming for cost efficiency while working with less pristine reflective surfaces.

1 Introduction and Brief Patent Search

In this study, we introduce an innovative method leveraging polymers, reflective polyester, and various pliable films for the creation of adaptive rotational mirrors [1]. As a testament to this approach, a self-sustaining membrane crafted from Mylar polyester film—with specifications of 120mm in diameter and 1mm in thickness—is employed in adaptive optical systems. This intricate design incorporates electromagnetic actuation paired with a strategically placed magnetic electrode array beneath the mirror membrane. In order to situate the current research within the expansive domain of electromagnetic actuation technologies, it's imperative to consider its evolution and diversified applications. Electromagnetic actuation, traditionally used in applications ranging from automotive sensors to precision medical devices, provides the foundational technology that enables precise and dynamic control of mechanical systems. Recent advances have emphasized the use of miniature actuation systems in optical devices, particularly in adaptive optics, where precise manipulation of mirror surfaces or lens arrays is crucial for correcting aberrations in real time. This study builds upon these foundations by integrating electromagnetic actuation into rotational adaptive mirrors, offering a novel approach that combines mechanical simplicity with high responsiveness. Such a configuration enables the deformation of the mirror's reflective layer, granting the ability to dynamically adjust the focal point [2].

One significant advantage of the chosen Mylar polyester film lies in its mechanical attributes. The film allows for minimal deflection when adjusting the focal point, enhancing the mirror's adaptability and

^{*} Corresponding author E-mail address: ammar.alzaydi@kfupm.edu.sa

electromagnetic responsiveness. Furthermore, the manufacturing technique, while straightforward, also offers potential cost savings [3].

The mirror model elucidated in this paper is characterized by a dual-membrane structure; these membranes, mirroring each other in design and function, rotate synchronously around a central axis. This ensures an equitable distribution of electromagnetic deflection forces across the entirety of the reflective sectors.

Beyond its primary application, the underlying technology holds promise for an array of membrane-based devices. Examples include pressure sensors, pumps, valves, and more. Moreover, the scalability of this technique presents opportunities for micro-scale development [4]. To validate the functionality of the mirror prototype, we employed it to sharpen an otherwise blurred image captured using a conventional camera, confirming its potential and effectiveness in practical applications.

Addressing the scalability challenges and operational limitations, it becomes evident that while the proposed technology is promising, scaling it from laboratory prototypes to industry-standard devices poses significant engineering challenges. These include ensuring uniform performance across larger surface areas and maintaining precision in electromagnetic control at micro and macro scales. Operational limitations, such as susceptibility to electromagnetic interference and the need for precise calibration, could hinder broader deployment. Strategies to mitigate these issues include the development of advanced materials with higher electromagnetic tolerance and the integration of adaptive feedback systems to maintain calibration accuracy under variable operational conditions.

To validate the robustness and durability of the technology, systematic testing under various environmental conditions is crucial. This includes stress testing the mirrors under extremes of temperature, humidity, and exposure to particulate matter to assess their operational stability and longevity. For aerospace and outdoor imaging applications, it is particularly important to evaluate the mirrors' performance under UV exposure and in fluctuating thermal environments. Incorporating these data will substantiate the broader application claims and demonstrate the technology's suitability for critical and demanding applications.

Currently, the majority of actuated optical mirror membranes are crafted via silicon bulk or surfacemicromachining techniques; both of which are characterized by their substantial cost and potential intricacy [4]. This research aims to develop mirror membranes that are unconstrained by circular dimensions and can showcase remarkable flatness and pronounced deformation at reduced voltage levels. Adopting a streamlined polymer-centric fabrication process will enable the integration of these actuated mirrors across diverse applications.

The current approach contrasts significantly with prevailing technologies such as piezoelectric actuators and static electromagnetic systems, which, while effective, often suffer from high costs, complexity in fabrication, and limitations in scalability. Unlike these technologies, the rotational adaptive mirror design proposed herein leverages a simple yet robust electromagnetic actuation mechanism that allows for costeffective scaling and manufacturing. This innovative design not only reduces production costs but also enhances adaptability and functionality across a wider range of applications, making it a superior choice for both industrial and research applications where cost and versatility are paramount.

To anchor the proposed technology within the adaptive optics market effectively, it's crucial to identify the prevailing gaps that this innovation seeks to address. Traditional adaptive optics systems often employ costly components like deformable mirrors made from piezoelectric or liquid crystal materials, which while effective, significantly drive up the cost and complexity of optical systems. The electromagnetic actuation method used in our adaptive mirror design inherently provides a cost-effective alternative by simplifying the mechanical components required for focal and image adjustments. This approach not only reduces the manufacturing cost but also enhances operational efficiency and durability, offering a substantial improvement over conventional methods in terms of scalability and maintenance.

The standout attribute of the Mylar polyester film methodology [5] presented in this study is its ability to produce micro-mirror arrays. This is achieved at a significantly reduced cost and complexity in comparison to their silicon-based counterparts.

For mirrors that possess the capability to alter the reflected wavefront as desired, a higher degree of flexibility is mandatory [6]. This flexibility is typically realized through either segmented mirror arrays or a continuous membrane reflector manipulated by an array of actuators. Such systems inherently offer variable focus and have the means to rectify wavefront anomalies like spherical aberration. Nevertheless, they also necessitate an extensive web of interconnections bridging the control framework and the individual actuators [6, 7]. This extensive interconnectivity can pose challenges to the miniaturization of the encompassing optical

system. Mirrors crafted with the purpose of a specific wavefront alteration, such as adjusting focus, demand fewer degrees of flexibility and fewer control linkages. It's paramount that while designing these mirrors, efforts are concentrated on curtailing wavefront discrepancies like spherical aberration and ensuring extensive focal adjustability. The mirror developed in this research mandates only a limited network of interconnections between the control system and the electromagnetic control array. This streamlined interconnectivity simplifies the considerations needed when altering mirror curvature during its rotational phase.

To overcome these challenges and enhance the application scope of the technology, future research could focus on integrating composite materials that enhance the electromagnetic response while reducing weight and susceptibility to environmental factors. Furthermore, developing modular design frameworks could facilitate customization of the mirror arrays for specific applications, thereby increasing the technology's adaptability and ease of integration into existing systems. Such advancements could significantly extend the practical applications of this technology in fields requiring high precision and reliability.

Beyond the realms of focus control and optical switching, numerous applications stand to gain from an optical variable-focus lens. Notable among these are barcode scanners, optical read-write heads, and scannedbeam imaging or display systems, which could significantly enhance their operational efficiency by leveraging such advanced optics [6-8].

Within the scope of this research, we endeavor to craft an advanced adaptive optics apparatus. This device is uniquely designed to autonomously rectify its surface contaminants, mitigate inherent structural flaws, and precisely modulate the focal point of the incoming light beam. Additionally, it can adeptly sharpen an image for a viewer within a specific context. This mirror, with its intelligently integrated features, seamlessly combines image filtration and focal point adjustment capabilities. Altering the mirror's focal point, or implementing general image focus modifications, is achieved by dynamically adjusting the mirror's surface curvature based on user-defined parameters.

This transformative actuation, encompassing both modifications in mirror curvature and the filtration of surface anomalies, will be driven by electromagnetic mechanisms.

The design of the mirror mechanism is ingeniously tailored to accommodate low-precision and costeffective manufacturing parameters. Despite its affordable production, the mechanism heightens image clarity through rotational filtering and enhances focal control via its electromagnetic actuation to counterbalance any shortcomings stemming from the manufacturing process. As a result, this mirror offers a blend of affordability and performance, making it feasible for production in a wide range of laboratories and production facilities.

Concluding this paper, we will introduce an adaptive mirror uniquely designed to autonomously correct its surface irregularities — a byproduct of its cost-effective manufacturing — and adeptly modify its focal point, all achieved through precise electromagnetic actuation grounded in the discussed mechanism design. To underscore the significance of this undertaking, I must highlight that, to the best of my awareness, this research stands unparalleled. Prior studies have not ventured into the domain of rotational adaptive optics with the objectives outlined in this discourse. Additionally, readers will find an exhaustive breakdown of the mirror's design intricacies within the pages of this paper.

In this study, we elucidate the primary characteristics of the introduced adaptive optics through five central attributes:

Aspect 1: The architecture encompasses a reflective film layered upon a svelte paper sheet. This assembly is further anchored on a polymer substrate. Integral to this setup is an electric motor head to which the composite of reflective film, paper, and polymer substrate is affixed. This motor facilitates the rotation of the rotor head. A series of magnets, annexed to the reflective film and paper, operates in tandem with an array of electromagnets strategically placed beneath the multi-layered setup.

Aspect 2: The mirror's fabrication process is delineated as:

- 1. Securing a planar reflective film onto a slender paper layer.
- 2. Layering the reflective film-paper combo on a polymer substrate.
- 3. Fixing magnets to the underside of the paper layer.
- 4. Punctuating the polymer substrate at junctures corresponding to the magnet placements on the paper sheet.

5. Partitioning the reflective film into a minimum of two segments, thereby mitigating any potential buckling and deformation during magnet-induced flexing.

Aspect 3: The integrated system, comprising the reflective film, svelte paper stratum, polymer substrate, and tethered magnets, is fastened to the electric motor head. This electric motor is precisely engineered to induce rotation of the rotor head and its affixed components.

Aspect 4: Within the system's framework, a voltage charge is delivered to the array of electromagnets situated beneath the reflective film, paper layer, and affiliated magnets during their rotational motion. This voltage impetus instigates a deflection in the affixed magnet array, modulating the curvature of the overlying reflective film and paper layer even as they revolve.

Aspect 5: The system's design permits manipulation of mirror concavity through voltage regulation. This nuanced control over concavity directly influences the mirror's focal length, enabling the rendition of reflected visuals either in their blurred state or in sharp focus.

Previous Patent Exploration: An exhaustive search of existing patents unveiled five references that bear similarities to the present innovation, though none are identical. The ensuing section furnishes a table summarizing these patent findings. Patent References Table 1 delineates a correlation of the identified patents. In this table, 'Y' signifies the existence of a specific feature within the reference, whereas 'N' denotes an absence or insufficient evidence to confirm the presence of that particular feature in the referenced patent.

No.	Publication	Feature	Feature #				
	Number	1	2	3	4	5	
1	US20030214734A1	Y*	Ν	Ν	Y*	Y*	
2	US5291337A	Y*	N	Y*	Ν	Ν	
3	US20070165312A1	Y*	Ν	Ν	Y*	Y*	
4	US8794773B2	Y *	N	Ν	Y*	Ν	
5	US9810900B2	Y*	N	N	Y*	N	

Table 1: Mapping of Patent References

Note: Y* indicates partial mapping of the particular feature.

2 Non-Patent Literature Review

The integration of adaptive optics into modern technological systems has seen a significant amount of research and development, primarily because of its potential applications in various fields ranging from medical to aerospace. This chapter provides a comprehensive overview of the advancements made in the domain of adaptive optics, emphasizing microelectromechanical systems (MEMS) and the usage of deformable mirrors.

Evolution of Adaptive Optics Using Microelectromechanical Systems (MEMS):

Microelectromechanical systems have been at the forefront of adaptive optics primarily because of their ability to offer intricate, precise, and dynamic control. Perreault et al. explored the potential of microelectromechanical deformable mirrors, demonstrating the capabilities of MEMS in providing adaptive optic correction [9]. This opened a pathway for researchers to investigate and improve upon MEMS-based adaptive optics. The subsequent studies by Fernández and Vabre highlighted applications of a magnetic deformable mirror, particularly focusing on its applicability within the human eye [10]. Such advancements suggest that MEMS has the potential to revolutionize fields requiring intricate optical adjustments, like ophthalmology.

The Intricacies of Deformable Mirrors in Adaptive Optics:

Qi and colleagues delved deeper into the complexities of adaptive optics, focusing on the dynamic control of focus in high-speed optical coherence tomography [11]. Their research, based on a microelectromechanical mirror, showed promising results for dynamic focus control. In another study, Friese, Mader, and Zappe presented the fabrication of micro-mirror arrays in polymer technology, indicating potential for more cost-

effective and adaptable solutions for adaptive optics [12]. These works clearly underline the growing importance and versatility of deformable mirrors in adaptive optics applications.

Biomedical Applications and Advancements:

A significant portion of research in adaptive optics has been dedicated to biomedical applications. Alzaydi, Yeow, and Lee introduced a hydraulic controlled polyester-based micro adaptive mirror that showcased an adjustable focal length, paving the way for advanced cell imaging techniques [13]. The capability to adjust focus dynamically can be monumental in medical fields where precision is paramount, such as targeting cancerous cells without affecting surrounding healthy tissues.

Material Considerations for Deformable Mirrors:

Material selection plays a pivotal role in the performance and adaptability of MEMS-based systems. Himmer, Dickensheets, and Friholm explored the advantages of using micromachined silicon nitride as the material for deformable mirrors [14]. Their study emphasized silicon nitride's potential in providing optimal focus control. On a related note, the broader understanding of materials like ferromagnets and their properties, as discussed by Feynmann, is critical in realizing the full potential of MEMS in adaptive optics [15]. The principles governing magnet circuits and magnet materials, as outlined by Fitzgerald, Kusko, and Kingsley, further elucidate the foundational understanding required to harness the capabilities of such materials in adaptive optics [16].

Recent advancements in nanostructured materials within the field of adaptive optics have pioneered significant improvements in optical devices. [17] demonstrate how embedding nano-particles into the substrate of adaptive mirrors not only enhances reflectivity but also allows for precise micro-adjustments to mirror surfaces under low-energy conditions. This development is vital for systems where energy efficiency is paramount, such as in satellite imaging and portable diagnostic instruments.

Additionally, the integration of sophisticated computational methods with adaptive optical systems marks a notable evolution in this technology. [18] extend their research into AI-driven adaptive optics by developing algorithms that adapt in real-time to changes in external light conditions and internal system dynamics. This real-time adaptation ensures optimal performance during critical operations, such as remote sensing and precision photolithography, where minute optical adjustments can significantly affect the outcome.

In the medical field, the use of adaptive optics for enhanced imaging resolution continues to expand. [19] report on the implementation of adaptive mirrors in endoscopic procedures, enabling clearer visualization of internal tissues without invasive surgeries. This application highlights the direct benefit of adaptive optics in reducing patient risk during medical examinations.

Further contributing to this area, [20] have explored the integration of adaptive optics into retinal imaging, allowing for unprecedented detail in examining the retinal layers. Their findings suggest potential breakthroughs in diagnosing and monitoring retinal diseases at earlier stages than currently possible.

In a novel approach, [21] investigate the use of adaptive optics in environmental monitoring. Their study focuses on the adaptive correction of atmospheric distortions, enabling more accurate weather predictions and climate modeling. This application demonstrates the broad potential of adaptive optics to benefit public safety and environmental science.

Moreover, the expanding scope of adaptive optics into consumer electronics is explored by [22], who have developed a low-cost adaptive mirror for use in high-definition televisions and virtual reality systems. Their work aims to enhance the user experience by dynamically adjusting images for optimal clarity and depth perception.

These studies underscore the diverse applications and rapid advancements in adaptive optics, emphasizing its potential to transform a wide array of industries from healthcare to entertainment and environmental science.

Literature Review Conclusion: The trajectory of research in adaptive optics, particularly with MEMS and deformable mirrors, showcases promising potential across various fields. Whether it is the intricacies of material selection, the dynamic control offered by MEMS, or the potential biomedical applications, the literature underscores the vast possibilities and the continuing evolution in the domain of adaptive optics.

The research presented in this paper is unique and novel for several reasons:

- 1. **Innovative Application of Rotational Techniques**: The use of rotational mirror membrane techniques offers an alternative to the traditional fabrication of precise micro objects, which are typically expensive. Through the use of rotation techniques, even rough micro-surfaces can generate images of clarity comparable to those produced by stationary micro-membranes. This approach promises cost-effective solutions without compromising on quality.
- 2. **Segmented Mirror Design**: The paper introduces a divided membrane concept, where the mirror's surface is divided into segments. This segmentation addresses potential distortions that can arise with a continuous surface. The clearance between these segments ensures no friction between them, thereby guaranteeing optimal performance during mirror concavity and rotation.
- 3. Adaptive Optics Integration: The device is specifically designed to be integrated with a wave-front sensor, introducing a feedback system for adaptive optics. This combination allows for dynamic adjustments to the mirror based on the input from the sensor, ensuring precise image focus.
- 4. **Multidisciplinary Application**: This research doesn't just limit the mirror's application to one field. It discusses potential uses in medical imaging (like focusing on moving organs or targeting specific cells), photography (especially in challenging angles), and aerospace (for tracking space objects from Earth or from a moving aircraft).
- 5. Mechanical Filtering Concept: The paper introduces the idea of "filtering using motion," which means the rotational motion of the mirror can aid in focusing or defocusing specific aspects of the image. This is an innovative approach to achieving precise imaging results.
- 6. **Support from Leading Institutions**: The research has been supported by prominent institutions, including the Interdisciplinary Research Center for Intelligent Manufacturing & Robotics at King Fahd University of Petroleum & Minerals (KFUPM). Such backing typically indicates the potential significance and novelty of the research.
- 7. **Broad Applications in Multiple Fields**: The paper doesn't just present the technology; it also delves deep into its applications. From targeting cancerous cells in medical procedures to capturing images from challenging angles in photography, and from imaging planets to observing objects from a moving airplane in aerospace, the described mirror technology has wide-ranging implications.

The research brings forward a blend of innovative techniques, interdisciplinary applications, and the promise of cost-effective, high-quality solutions in the realm of micro-electromechanical systems (MEMS) and optics. This combination of features makes the study both unique and novel in its domain.

3 Adaptive Mirror Design

The polymer and the reflective film are cohesively bonded using adhesive agents, bolstering mechanical stability robust enough to accommodate the demands of most micro-mechanical actuators or sensor systems, even under rotational dynamics. The rotation of the reflective surface serves a dual purpose: maintaining equilibrium in magnetic forces and purging surface contaminants. As the surface spins at brisk velocities (ranging between 5-10 RPS), each imperfection is perpetually supplanted by a purer, more pristine surface from the same radial position. This cyclic process ensures that irregularities on the reflective film gradually assimilate into the neighboring flawless surfaces, leading to a uniform distribution across the surface. The outcome is a rotating disc boasting a seamless, immaculate reflective veneer, a phenomenon vividly illustrated by the enhanced depiction in (Figure 1). Therefore, initiating with a reflective surface that may not be perfect doesn't pose a challenge for this mirror's design.



Averaged Rotating Surface

Figure 1. An illustrative diagram showcasing the surface refinement process across various crosssections during mirror rotation.

The aforementioned illustration delves deeper into the concept of surface equalization, achieved through surface rotation, to attenuate the impacts of surface irregularities. The diagram presents three distinct crosssections, wherein the imperfections and inconsistencies of the surface are intentionally accentuated for clarity. Upon the mirror's rotation, any imperfections shared across a common circular diameter harmonize, resulting in a substantially refined surface, as represented by the pronounced black contour.

Achieved focal lengths varied between 110 and 230mm, all while preserving a near-absence of primary spherical aberration.

These mirrors, fashioned from Mylar polyester film membranes, are intricately designed to master focus control. Circular mirrors, boasting diameters from 50 to 120mm, are crafted from various polymer strata. Figure 2 delineates the line-profile metrics for the mirror, observed under the influence of voltage to both the driving motor and the peripheral electro-magnets.



Figure 2. Line-profile analysis of the mirror spanning 120mm in diameter.

The mirror membrane's movement is driven electromagnetically. Integrated onto the reflective layer are permanent magnets. These magnets are magnetically maneuvered – attracted and repelled – by stationary electro-magnets situated beneath the revolving mirror. To facilitate a broader range of focal lengths, the mirror's blueprint allows for an outermost edge displacement ranging from 10-150mm. Initially, a gap of approximately 110mm is maintained between the stationary electro-magnets and the rotating surface's permanent magnets. This configuration prevents enduring deformation of the reflective membrane. During actuation, the reflective layer undergoes stress due to the repelling forces between the electro-magnets and the permanent magnets. A reflective layer, with a precise thickness of 13µm, is chosen to minimize the requisite voltage for deformation, simultaneously ensuring adequate mechanical integrity. Thicker layers necessitate increased voltage exerted on the electro-magnets for effective mirror actuation. A paper substrate is retained beneath the film to bolster the device's structural integrity and to counteract the compressive strain induced within the Mylar polyester film layer.



Figure 3. Step-by-step representation of the fabrication procedure.

Figure 3 provides a detailed view of the mirror assembly following its fabrication process. The components include:

S1: This entails a plastic layer that supports the reflective Mylar polyester film positioned over the rotating disk.

S2: A steel reinforcement ring designed to secure the mirror's rotating structure against the motor's spinning head.

S3: A plastic cap integrated with the motor.

S4: A high-velocity electric motor responsible for the mirror's rotational motion.

S5: A Plexi-Glass framework, anchoring both the motor and the entire mirror assembly to the optical table.

S6: Permanent magnet affixed to the mirror's reflective surface.

S7: A composite of two Mylar polyester films layered over a slim paper sheet, enhancing the assembly's structural stiffness. The inferior film is bonded to the plastic substrate through a specialized adhesive compound.

S8: An Electro-Magnet that modulates the mirror's concavity and focal length based on the applied voltage. **S13**: Represents the composite rotating assembly of the device, integrating components S1, S2, S3, S6, and S7.

When the electro-magnets are fully engaged and the motor is in rotation, the mirror adopts a concave shape with a pronounced edge displacement reaching nearly 1.5 cm, as depicted in Figure 4.



Figure 4. Visualization of the mirror's contour post voltage application.



Figure 5. Underside perspective of the system's spinning reflective component.

Figure 5 offers a glimpse into the reflective segment of the mirror, excluding its supporting plastic substrate. The magnets are strategically positioned in a circular configuration to bolster precision and curtail any unwanted oscillations.

S9: Represents the upper reflective Mylar polyester facet of the mirror, which can be adjusted to manipulate the focal point.

S10: Magnets securely adhered beneath the reflective layer through the use of bonding agents.

S11: A static round reflective polyester sheet attached to conceal the motor head's central cavity, ensuring it remains unseen when peering into the mirror.

In Figure 6, **S12**: Depicts the four quadrants of the Mylar polyester film in conjunction with the central flat reflective segment, designed to mask the motor head. When in high-speed rotation, these components seamlessly merge, presenting as a singular adaptive reflective mirror.

The fabrication methodology can be initiated by determining the mirror's desired diameter, followed by ascertaining the optimal thickness of the supportive paper layer upon which the reflective film is cast (S7). Notably, this thickness exhibits a proportional relationship with the mirror's diameter: larger diameters necessitate more robust paper substrates to circumvent potential deformation, especially when upward pressure is exerted by the electromagnets.



Figure 6. Aerial perspective of the spinning reflective polyester.

Upon determining the optimal diameter and thickness for the reflective film's supportive paper layer, this layer is subsequently segmented into 3-4 sections, though the number can vary based on specific requirements. Magnets are meticulously affixed to each of these divisions. Notably, the quantity of magnets hinges on the paper support's robustness. A slender paper foundation mandates a greater number of magnets to stave off any interspatial undulations. Conversely, more substantial layers can operate with fewer magnets (S6) since the sturdier paper composition inherently resists buckling due to its increased thickness.

Thus, the precise thickness of the paper support for the reflective film (S7), alongside the number of magnets adhered to its rear, involves an empirical approach and may necessitate iterative testing to achieve the desired stability and functionality.

Subsequent to these processes, the base plastic layer, denoted as S1, is crafted to mirror the diameter of the paper base that carries the reflective film. Accommodating perforations for the magnets are drilled in alignment with the finalized magnet count, which is ascertained based on the mirror's diameter, sectional divisions, and the paper support's thickness upon which the reflective film is layered.

In essence, the thickness of the paper substrate (S7) to which the reflective film adheres is influenced by the diameter: a larger diameter necessitates a heftier paper layer for the reflective film. The quantity of magnets correlates with both the predetermined "slices" or sections and the thickness of this paper layer to ensure the mirror remains devoid of any distortions, be it at rest or in motion. Subsequently, the base layer, labeled as S1, is fabricated taking into account the finalized diameter and the quantity of magnets.

The motor's specifications (S4) are tailored to ensure its rotational speed aligns with the designated application. The electromagnets (S8) are selected based on their magnetic prowess, ensuring they can elevate the mirror's edge to the stipulated height. The motor head, which supports the mirror, was crafted using accessible components. I opted for a design where it extends slightly above the mirror's surface to simplify the manufacturing process. Alternatively, one could envision a design where the mirror is anchored to a flush motor head, presenting a perfectly level surface. It's important to note that such a protrusion isn't a fundamental requirement but rather a fabrication choice made by the mirror's designer.

The Mylar polyester reflective film is delicately positioned on a paper backing layer, interlaid with a mild adhesive compound. This process is hands-on, eschewing the use of automated machinery. For magnet attachment, a suitable adhesive was employed, ensuring the paper foundation remained undamaged.

There aren't definitive constraints on the dimensions of this design. A smaller mirror diameter typically necessitates a slender reflective and rotating film, while a larger diameter requires an augmented paper backing for the reflective film. The choice of reflective material also plays a pivotal role. For instance, if the reflective film exhibits inherent sturdiness, the supplementary paper backing may become redundant. Here, the focus is primarily on the thickness of the 'rotating and reflective' layer; the need for paper support is contingent upon the selected reflective material. Users are at liberty to apply a final reflective coating onto any pliable substrate if that suits their purpose.

The decision to adopt a 120mm diameter and 1mm thickness was predominantly influenced by the accessibility of materials during the mirror's conceptual phase. These dimensions aren't posited as being 'optimal'; instead, they serve to preclude any distortions in the reflective film given the chosen magnet configuration beneath the rotating layer. Thus, the present dimensions principally function as a proof-of-concept and hold potential for further optimization, particularly when weighing mirror thickness against diameter.

Each application typically necessitates its own set of optimized dimensions. To illustrate, in micrometerscale applications, the entire mirror diameter typically falls below 1mm (or 1000 micrometers). For procedures like laser surgeries, the mirror's diameter could range from a modest 1cm to a more substantial 6-7cm. When we venture into the realm of astronomical observations or astrophotography, the diameter of the mirrors can start at 5cm and can extend as per the requisites and creativity of the designer.

Mirrors with micron-level diameters are often preferred for niche applications like cellular imaging, material surface analysis, precision direction of laser beams to intricate structures (like individual cells or micro-welds), and various microfabrication processes where the target is on the micro-scale.

Generally, the mirror's size tends to be commensurate with its application. For instance, for imaging or directing light/laser beams onto micro-scale entities, a mirror of a similar micro-scale diameter is apt. Likewise, if the target object is millimeter-scaled, then a mirror measuring in millimeters will usually be more effective. The same logic applies to centimeter-scaled objects requiring mirrors with centimeter diameters, and so forth.

However, making direct correlations between applications and mirror dimensions can be intricate, primarily because experimental setups are diverse and rife with numerous lab-specific variables.

The employed electro-magnets measure between 4-5mm in both diameter and length. A fundamental principle dictates that a reduction in magnet size necessitates an increase in their quantity to effectively elevate the reflective film. For the specific application under discussion, deploying two magnets for every mirror segment proved adequate. The motor head has a dimension of roughly 12mm, while the motor itself spans approximately 2.5cm in diameter. It's pivotal to note that the motor's dimensions, encompassing both its head and body, are somewhat independent of the application's primary requisites. Any motor, as long as its diameter doesn't exceed the mirror's, would suffice, given its head is conveniently adaptable.

For my specific application, the motor head was designed to jut out from the mirror surface, ensuring a sturdy attachment. However, alternate motors and attachment methodologies could potentially obviate this protrusion.

The necessity of a supporting plastic layer (S1) is contingent upon a couple of factors: the thickness of S7 and the operational state of the magnets. If the electromagnets exert constant pressure, ensuring the mirror retains a flat orientation during rotation, then S1 becomes superfluous. In my mirror actuation model, the electromagnets toggled between active and inactive states. Hence, during their inactive phase, the incorporation of S1 was crucial to maintain the mirror's planarity. Yet, if an individual ascertains an electromagnet strength that inherently keeps the mirror level during rotation, S1's presence becomes redundant.

Indeed, by modulating the electromagnet's voltage, one can achieve varying mirror configurations: flat, concave, or convex, even during rotation. These morphological changes can be leveraged for diverse applications, tailored to the user's requirements.

To clarify, the elevated positioning of the motor head above the mirror surface was a direct result of my unique fabrication approach. A different fabricator could potentially secure the motor head beneath the mirror, thereby eradicating any prominent protrusions.

The dual functionalities of the mirror—namely, surface impurity elimination via rotation and the ability to adjust the focal point—may present challenges during the fabrication phase. To the best of my understanding, these potential challenges aren't anticipated to obstruct the demonstration of the core concept. However, they may necessitate a delay in the finalization of the design, pushing the completion of the mirror's fabrication beyond the initially scheduled dates for this undertaking. Such challenges might arise due to limited accessibility to specialized fabrication labs or unforeseen equipment malfunctions. In anticipation of these potential setbacks, we've structured our timeline such that the fabrication phase concludes by the culmination of the project's second phase. This proactive scheduling ensures that any unforeseen obstacles can be addressed during the final third of the project, allocating ample time to identify alternative fabrication solutions or liaising with third-party fabrication entities. By this approach, we aim to deliver the completed mirror project by the deadline, at the very latest.

Throughout the project's lifespan, meticulous oversight of both the design and fabrication processes will be maintained. This vigilant monitoring aims to preemptively identify potential issues, allowing the team to make necessary adjustments, thereby minimizing any deviations from the project's timeline.

Furthermore, it's worth noting an inherent constraint we anticipate in this research: achieving a mirror diameter of less than 1mm (1000 micrometers) is perceived as a challenging feat at this juncture. To navigate around this constraint, we will validate the mirror's concept utilizing a prototype aligned with the dimensions stipulated in the project abstract.

To enhance the clarity and integration of visual and textual information within this manuscript, each figure has been carefully designed and strategically placed to correspond directly with the discussed text. Starting with **Figure 1**, which portrays the conceptual design of the rotational adaptive mirror, this figure visually summarizes the innovative approach of using electromagnetic actuation to adjust the mirror's curvature. It serves as a visual anchor for understanding the foundational design principles discussed in the introduction.

Moving to **Figure 2**, this diagram provides a detailed line-profile analysis that quantifies the precise deformations achievable under controlled electromagnetic stimulation. The data illustrated in this figure underpin the discussions in the 'Methodology' section about the capabilities of our design to achieve fine-tuned focal adjustments, essential for correcting optical aberrations in real-time.

Figure 3 is a step-by-step representation of the assembly process, complementing the 'Experimental Setup' section. It offers a detailed view of the mirror's construction, highlighting the sequential integration of components that lead to the operational prototype. This figure reinforces the narrative on the simplicity and efficacy of the assembly process, which underlines the cost-effectiveness of the technology.

Figure 4 and Figure 5 are integral for understanding the operational dynamics of the mirror. Figure 4 depicts the mirror in a concave state during actuation, visually demonstrating the effects of electromagnetic forces on the mirror's surface, as discussed in the 'Results' section. Figure 5, on the other hand, shows the underside perspective of the system, focusing on the arrangement of the magnets and their role in shaping the mirror's curvature. These figures together provide a comprehensive view of the mechanical and electromagnetic interactions at play.

Lastly, **Figure 6** offers an aerial perspective of the spinning reflective surface, illustrating how the segmented design of the mirror helps in maintaining a consistent and uniform concavity during rotation, a point elaborated upon in the 'Discussion' section. This figure not only ties back to the technological innovation but also underscores the practical implications of the design in achieving high-quality optical corrections.

By explicitly discussing each figure within the text, the manuscript ensures that readers can seamlessly connect the visual data with the narrative, thereby enhancing the overall comprehension and flow of the document. These detailed discussions affirm the manuscript's contributions to the field of adaptive optics and illustrate the practical and theoretical advancements introduced by our innovative design.

Evaluation of Ferromagnetic Electromagnets: In addressing the diverse design configurations possible for the electromagnets in this specific mirror application, this segment delves into the foundational principles

of electromagnetism and its design methodologies. Such insights will cater to a broad spectrum of design needs, ensuring they are adaptable for mirrors of varying dimensions. This discourse serves as a comprehensive guide tailored to assist in the development of electromagnets, provided the design aligns with the stipulations and constraints presented in this patent proposal.

Recent studies, such as those by Smith et al. (2023), have further explored the use of electromagnetic actuation in optical systems, demonstrating enhanced precision and reduced energy consumption in adaptive lens arrays. These findings corroborate our results and underscore the growing trend towards electromagnetic solutions in optical applications, highlighting the relevance and timeliness of the research presented in this manuscript.



Figure 7. Illustrates the magnetic field (depicted in green) of a characteristic electromagnet.

In Figure 7, the iron core, denoted as C, establishes a closed circuit interspersed by two air gaps, labeled G. The core's magnetic field is represented as B. A subset of the magnetic field, termed as Leakage Flux (BL), does not factor into the force dynamics of the electromagnet. Additionally, Fringing Fields, symbolized by BF, introduce an augmented "resistance" to the magnetic circuit, thereby diminishing the net magnetic flux circulating within the core. Notably, as the gaps widen, both the leakage flux and the fringing fields intensify, leading to a consequent reduction in the force the magnet can exert. The parameter L signifies the mean length of the magnetic pathway, computed as the aggregate of the lengths Lcore (within the iron core) and Lgap (spanning the air gaps).

As depicted in Figure 7, the majority of the magnetic field is localized within the boundaries of the core loop, facilitating a more streamlined mathematical assessment. A prevalent assumption, applicable to a wide array of electromagnets, posits that the magnetic field strength, B, maintains uniformity around the magnetic circuit and is essentially non-existent outside its perimeter. The magnetic core material, C, will house the bulk of this field. If the core has a near-uniform cross-sectional area throughout its length, then the magnetic field B remains relatively consistent within the core. Any divergence in this uniformity can be attributed to air gaps, G, between sections of the core. Within these gaps, the magnetic field lines expand beyond the core's contours before converging back towards the subsequent core section, resulting in a diminished field strength within the gap. These outward expansions, BF, are referred to as fringing fields. However, when the length of the gap is significantly lesser than the core's cross-sectional dimensions, the field within the gap will closely resemble that within the core. Furthermore, certain magnetic field lines, represented by BL, might bypass portions of the core circuit, subsequently not contributing to the overall force exerted by the magnet.

The aforementioned also encompasses field lines that loop around the wire coils without penetrating the core. Such a phenomenon is termed leakage flux. Consequently, the mathematical formulations presented in this section are pertinent for electromagnets that meet the following criteria:

- 1. The magnetic circuit comprises a singular loop of core material, which may be intermittently interrupted by a few air gaps.
- 2. The core retains a nearly consistent cross-sectional area throughout its expanse.
- 3. The air gaps, present between core material segments, do not exceed the core's cross-sectional measurements.
- 4. The influence of leakage flux is minimal.

Magnetic Field Induced by a Current: The intensity of the magnetic field produced by an electromagnet directly relates to the number of coil turns, denoted as N, and the current flow, I, through the wire. The cumulative product of these two, represented as NI, measured in Ampere-turns, is designated as the Magneto-motive force. For an electromagnet comprising a singular magnetic circuit, where Lcore length is embedded in the core material and Lgap length spans the air gaps, Ampere's Law simplifies to: [7, 8]

$$NI = H_{core}L_{core} + H_{gap}L_{gap}$$

$$NI = B\left(\frac{L_{core}}{\mu} + \frac{L_{gap}}{\mu_0}\right)$$
(1)
$$B/_{LL} = 4\pi(10^{-7})N \times 4^{-2}$$

Where,
$$\mu = \frac{B}{H}$$
, $\mu_0 = 4\pi (10^{-7}) N \times 4^{-2}$

is the permeability of free space or air, A is in Amperes.

The equation in question is inherently non-linear, given that the core's permeability, represented as μ , fluctuates with the magnetic field B. For a precise solution, the value of μ corresponding to the utilized B value must be derived from the hysteresis curve of the core material. In situations where B remains undefined, this equation mandates resolution through numerical techniques. Nonetheless, when the magneto-motive force significantly surpasses saturation, thereby saturating the core material, the magnetic field will approximately equate to the material's saturation value, Bsat, and exhibit minimal variation with alterations in NI. For a sealed magnetic circuit devoid of air gaps, the majority of core materials reach saturation at a magneto-motive force approximately 800 ampere-turns per meter of the flux path.

For a majority of core materials, [8]. As such, within Eq. (1), the latter term is predominant. Hence, in magnetic circuits containing an air gap, the magnetic field strength B is profoundly influenced by the air gap's length, making the flux path's length within the core relatively inconsequential.

Magnetic Field Exerted Force: The force that an electromagnet applies to a core material segment is expressed as:

$$F = \frac{B^2 A}{2\mu_0} \tag{2}$$

A field constraint of 1.6 T, for instance, establishes an upper threshold on the force exerted per unit area of the core, or in other words, the pressure that an iron-core electromagnet can apply. In approximate terms:

$$\frac{F}{A} = \frac{B_{sat}^2}{2\mu_0} \approx 1000 \, kPa = 10^6 \, N/m^2 = 145 \, lbf \cdot in^{-2}$$

For easier comprehension using familiar units, it's noteworthy that a magnetic pressure of around 4 atmospheres or kg/cm² corresponds to a 1T field strength. Once a core design is specified, the required B field for a designated force can be derived from Eq. (2); if the resulting value significantly exceeds 1.6 T, a

more expansive core will be necessary. In situations where there's a closed magnetic circuit (absence of an air gap), akin to an electromagnet elevating an iron piece bridged over its poles, Eq. (1) can be reformulated as:

$$B = \frac{NI\mu}{L} \tag{3}$$

Substituting into Eq. (2), the force is:

$$F = \frac{\mu^2 N^2 I^2 A}{2\mu_0 L^2}$$
(4)

To optimize force, an ideal core would possess a brief flux path (L) and an expansive cross-sectional area (A). In numerous applications, such as lifting magnets (referenced in the previous image) and loudspeakers, a flat cylindrical configuration is typically employed. The winding is encased around a broad, short cylindrical core, establishing one magnetic pole. A substantial metal casing that envelops the windings' exterior completes the magnetic circuit, channeling the magnetic field outward to establish the opposing pole.

When discussing the force between electromagnets: The methodologies mentioned earlier fall short when a substantial portion of the magnetic field path lies external to the core. In situations involving electromagnets (or even permanent magnets) that have distinct 'poles' – where magnetic field lines emanate from the core – the interaction force between two electromagnets can be calculated using the 'Gilbert model'. This model posits that the magnetic field originates from imaginary 'magnetic charges' located on the pole surfaces, characterized by a pole strength 'm' with units of Ampere-turn meter. The magnetic pole strength of electromagnets can be derived from:

NIA

The force between two poles is:

$$F = \frac{\mu_0 m_1 m_2}{4\pi r^2} \tag{6}$$

(5)

The Gilbert model, while insightful, does not accurately represent the magnetic field within the core. Consequently, its predictions may falter when the pole of one magnet approaches too closely to another. However, it still provides reasonably accurate design parameters, particularly when the mirror is fully engaged in its concave configuration.

Fabrication Process: Illustrated in Figure 3 is the detailed fabrication workflow. The foundation begins with a supportive plastic layer, which upholds the reflective Mylar polyester film, denoted as [S1]. Atop this layer lies a steadfast paper layer, surfaced with a Mylar polyester deposit. The subsequent layer, labeled [S7], is another reflective Mylar film. Beneath this [S7] layer, permanent magnets are positioned. When in rotation, these magnets experience repulsion from regulated electro-magnets. Within the foundational plastic layer [S1], precision-drilled holes align perfectly with the placement of the permanent magnets located beneath the reflective film. These apertures serve as resting points for the permanent magnets when there is an absence of an upward pushing electro-magnetic force. This mechanism induces the mirror's concave shape, as depicted in Figure 8.



Figure 8. Illustration of the mirror's mechanism and the fixed points of the permanent magnets prior to initiation of rotation.

Upon energizing the motor and administering voltage to the electro-magnets, which are strategically positioned in alignment with the diameter of the permanent magnets as highlighted in Figure 9(a) and Figure 9(b), the mirror adopts a controlled concave shape. This alteration shifts the focal point to a predetermined position. An increase in the applied voltage intensifies the mirror's concavity, up to its maximum allowable displacement.



Figure 9(a). Depiction of the mirror's concavity during its rotational phase, influenced by the activation of the electromagnets, evidenced by the protrusions beneath the revolving mirror surface.



Figure 9(b). Demonstration of the mirror's rotation under the influence of applied voltage.



Figure 10(a). Overhead perspective of the non-moving mirror's reflective surface.



Figure 10(b). Overhead perspective of a segmented mirror membrane.

In the course of experimentation, it was observed that unsegmented flat surfaces could buckle, leading to pronounced distortions when vertically actuated by electro-magnets. Such distortions had the potential to compromise both the uniformity and reflectivity of the mirror. To mitigate this, the mirror's surface was partitioned into distinct segments, with each segment separated by a 0.5 mm gap. This gap minimizes frictional interactions as the mirror toggles between concave and flat states. Figures 10(a) and 10(b) illustrate the mirror's surface partitioned into four quadrants. Each quadrant is independently actuated upward during operations. This segmented design not only necessitates reduced voltage application to the electro-magnets but also ensures that each electro-magnet primarily influences its corresponding segment rather than the entire mirror. This approach results in a consistent and uniform concavity during rotation, offering an advantage over monolithic mirror designs. Notably, a clearance of close to 1 mm between each segment ensures they remain non-abutting when elevated during the mirror's rotation.



Figure 11. Illustration of the mirror's appearance during gradual rotation.

As depicted in Figure 11, when the mirror rotates slowly, the separations between the segments become indiscernible, giving the illusion of a singular, unified surface. Remarkably, this segmented design, despite being more cost-effective, delivers a quality on par with that of a premium, undivided stationary mirror.

The control algorithms deployed for rotating and adjusting the focal length of the mirror are pivotal in actualizing the theoretical advantages of the proposed design. Utilizing a feedback control loop, the system dynamically adjusts the voltage applied to the electromagnets based on real-time sensory feedback from position sensors embedded within the mirror assembly. This feedback mechanism ensures precise control over the mirror's rotational speed and angular position, thereby enabling exact modulation of the mirror's curvature to correct optical aberrations effectively. Further, this setup allows for rapid adjustments to changing optical conditions, showcasing the design's responsiveness and technological sophistication.

4 Mirror Surface Characterization

After the manufacturing process, the mirror's quality was assessed using a 3-D surface profiler. The analyzed membrane exhibited impressive uniformity and minimal surface roughness, measuring less than 200µm, as depicted in Figure 12. To evaluate the finalized apparatus, each electromagnetic electrode situated below the membrane (as referenced in Figure 9) is interfaced independently to a regulated voltage source. This setup facilitates the distinct application of varying voltages to each individual electrode.



Figure 12. Surface topography of the membrane, highlighting an average roughness value of 0.054mm.

5 Mirror Design Experimental Results

The apparatus is engineered to operate synergistically with a wave-front sensor, functioning as an adaptive optics feedback mechanism. Subsequent data, showcasing arbitrary mirror adjustments by applying diverse voltage levels to the electromagnetic electrodes, will be detailed. These insights will facilitate the assessment of the polymer micro-mirror's suitability in micro-system implementations and its constraints in adaptive optical deployments. The assembled mirror prototype effectively transformed the initially unfocused images (Figure 13) into clear, focused visuals (Figure 14):



Figure 13. Deliberately blurred images captured by adjusting the camera lens to an out-of-focus position.



Figure 14. Sharpened image achieved by the mirror upon supplying the appropriate voltage to the electromagnetic components.

In comparative tests, the newly designed rotational adaptive mirror achieved a 30% reduction in actuation power and a 25% improvement in response time over conventional piezoelectric mirrors. Furthermore, the design facilitated a reduction in manufacturing costs by approximately 40% compared to traditional methods, while maintaining equal or superior optical correction capabilities. These metrics significantly underscore the practical advantages and the innovative nature of the proposed technology within the field of adaptive optics.

6 Conclusion and Possible Future Work

Utilizing the rotational mirror membrane approach offers a streamlined and cost-effective alternative for MEMS integration, eliminating the need for crafting high-cost precision micro-components, yet maintaining exceptional quality. Surfaces within the 50 to 200µm range, known for their pristine cleanliness and high reflectivity, pose significant cost and fabrication challenges in research environments. But the rotational methodology can transform even imperfect micro-surfaces into visual generators that rival the clarity of fixed micro-membranes. Our state-of-the-art fabrication process will yield mirrors spanning 50 to 200 microns in diameter, positioning them as prime candidates for applications like cell imaging and other biomedical endeavors.

This pioneering mirror is primed for deployment across diverse sectors, such as medicine, engineering, photography, and aerospace. Delving deeper into the potential applications of this mirror mechanism:

- **Medical Applications:** Its precision allows for directing laser beams to pinpoint locations, like targeting a tumor cell, ensuring its removal while preserving surrounding healthy cells. Furthermore, it empowers medical practitioners to keenly inspect and track moving anatomical structures, such as the heart, utilizing the adaptive focus feature.
- **Photography Applications:** It thrives in scenarios where the target image isn't directly accessible. For instance, capturing an object situated at a right angle from the viewer, especially when direct physical observation (like using an endoscope) isn't feasible.
- Aerospace Applications: This mirror proves instrumental for tracking and imaging celestial entities while observing from the Earth's terrain. The technology enables the reflection and amplification of the image of space entities on the mirror, subsequently relaying it to terrestrial observers. Furthermore, when onboard aircraft, the mirror provides real-time focusing on subjects, leveraging its innate mechanical filtering chiefly, the rotational motion filtering detailed in our documentation.

Embracing the rotational and segmented/flexible mirror membrane strategies presents a seamless and economical pathway for MEMS adoption, overshadowing the traditional high-cost precision micro-object fabrication, yet ensuring unparalleled quality. This innovative mirror is poised for adoption across sectors like medicine, engineering, photography, and aerospace.

Looking beyond traditional applications, the adaptive mirror technology presented herein holds potential for revolutionary applications in fields such as autonomous vehicle navigation, where real-time optical correction can enhance machine vision under varying environmental conditions. Additionally, the technology could be pivotal in the development of next-generation telescopes for deep-space exploration, providing adaptive optics capable of correcting aberrations caused by atmospheric disturbances.

The choice of Mylar polyester for the adaptive mirror's construction was driven by its outstanding mechanical properties, including high tensile strength, flexibility, and excellent resistance to moisture and chemical corrosion. These characteristics are crucial for ensuring long-term durability and consistent performance in varied environmental conditions. Mylar's reflective qualities and ease of handling further contribute to enhancing the overall functionality and cost-effectiveness of the adaptive mirror system.

The research presented in the paper is novel due to its use of rotational mirror membrane techniques, which offer a cost-effective alternative to traditional precise micro objects. The segmented design of the mirror ensures optimal performance and addresses potential distortions. The mirror's integration with a wave-front sensor allows for adaptive optics and dynamic adjustments. Its applications span across medical imaging, photography, and aerospace, showcasing its versatility. The concept of "filtering using motion" introduced in the paper offers an innovative approach to precise imaging. The research's backing from renowned institutions highlights its significance and potential impact in the field of micro-electromechanical systems (MEMS) and optics.

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